

coding  
lab

# RoboMaker<sup>®</sup>

výuková laboratoř robotiky

pro

X5•DROID

Konzultace  
vědeckého kódování  
a blokové  
programování: Prof.  
Alessandro Boqliolo



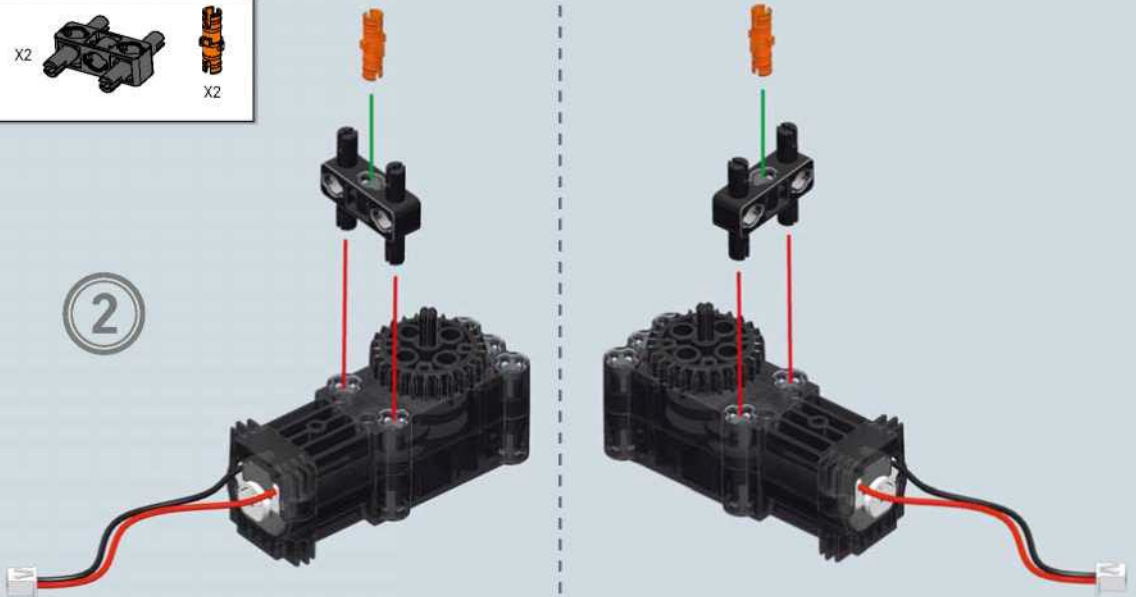
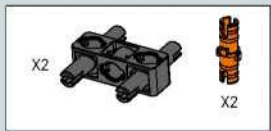
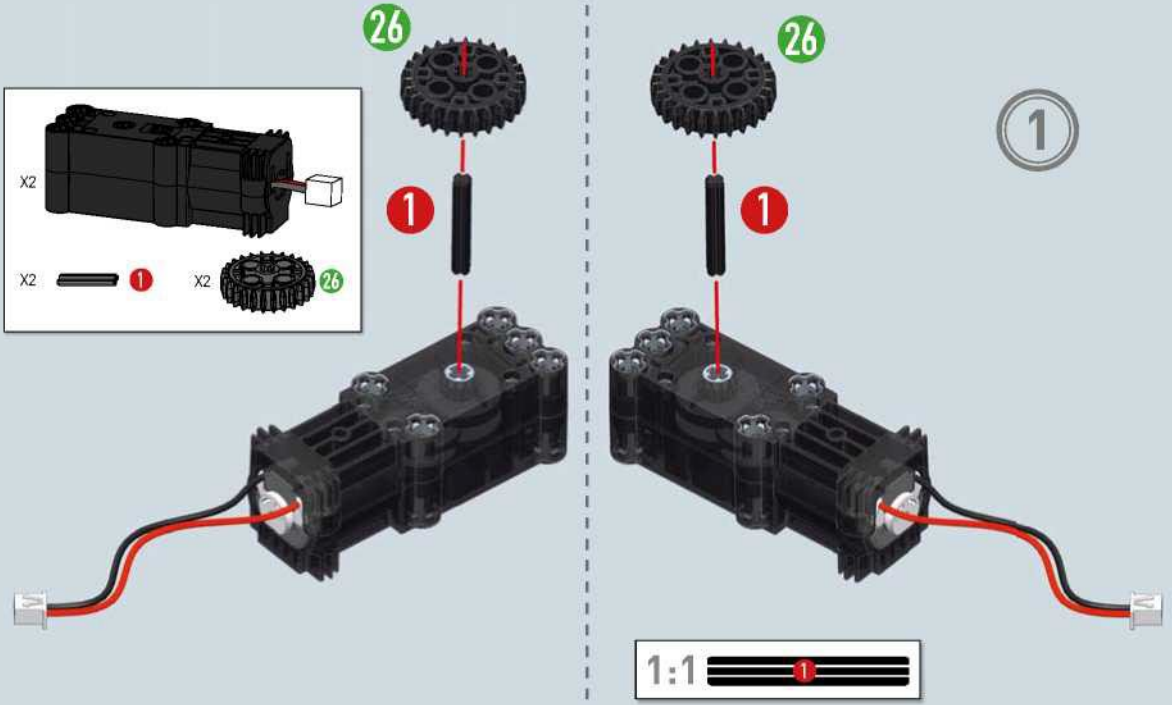
**PRODUCENT:**  
Clementoni S.p.A.  
Zona Industriale Fontenoce s.n.c.  
62019 Recanati (MC) - Italy Tel.:  
+39 071 75811  
[www.clementoni.com](http://www.clementoni.com)

advanced

Należy przeczytać Instrukcję i zachować ją do wglądu

**Clementoni**

Montáž



3



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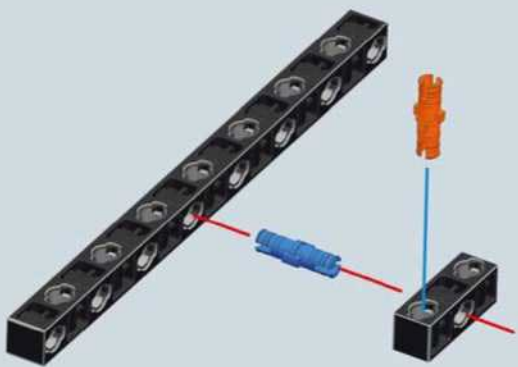
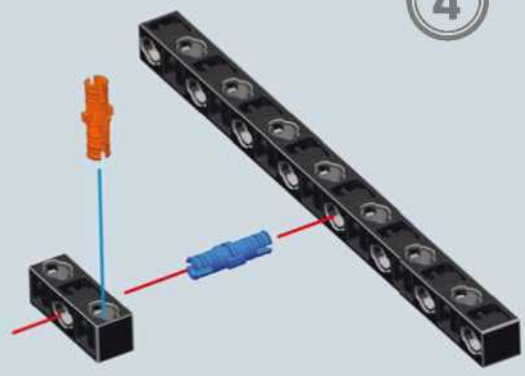
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- X2 6
- X2 10

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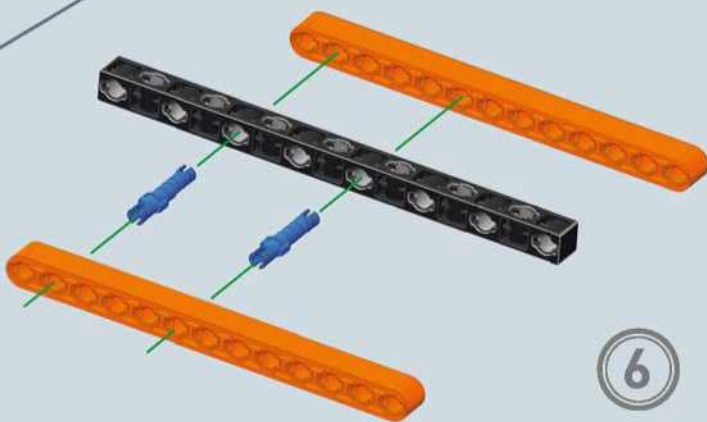
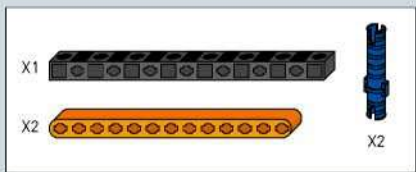


- X2 X2
- X2 6 X2 10 X2 X2



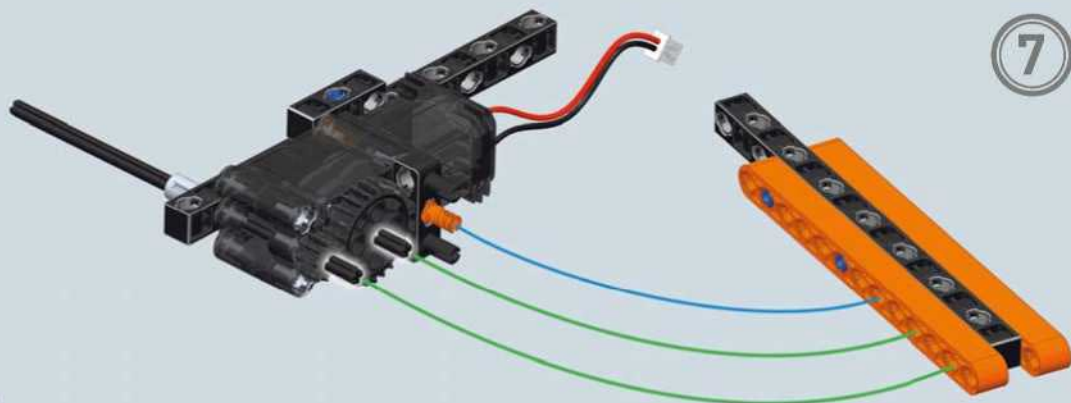
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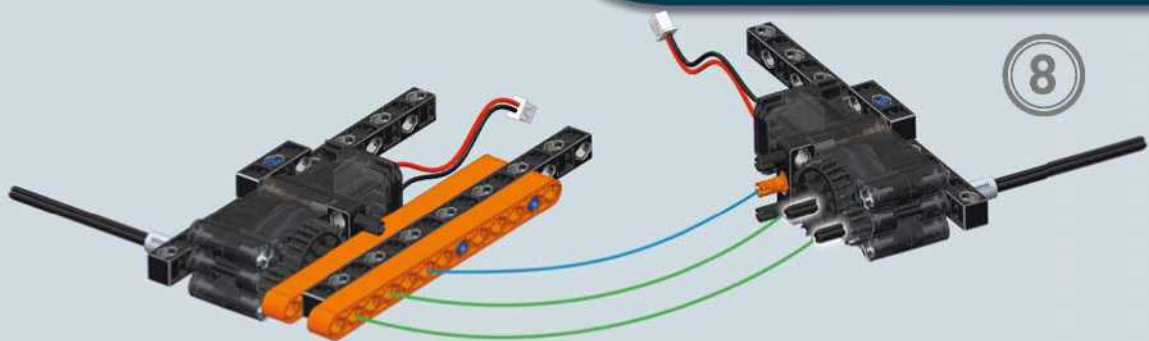


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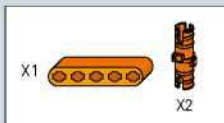
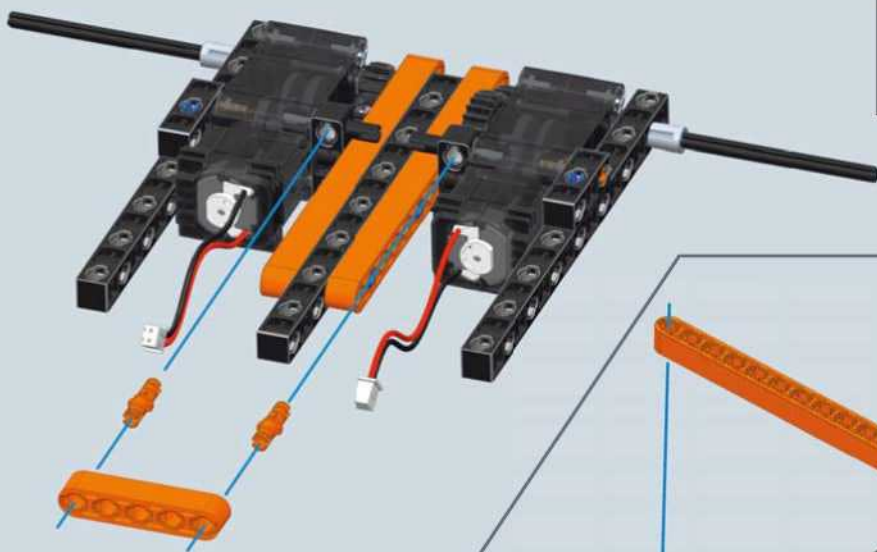
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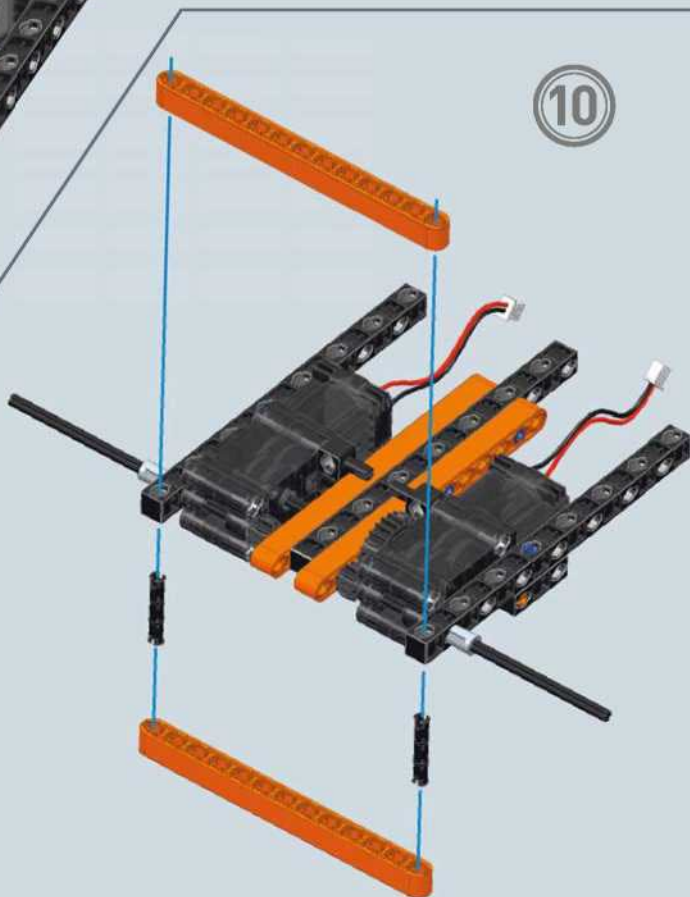
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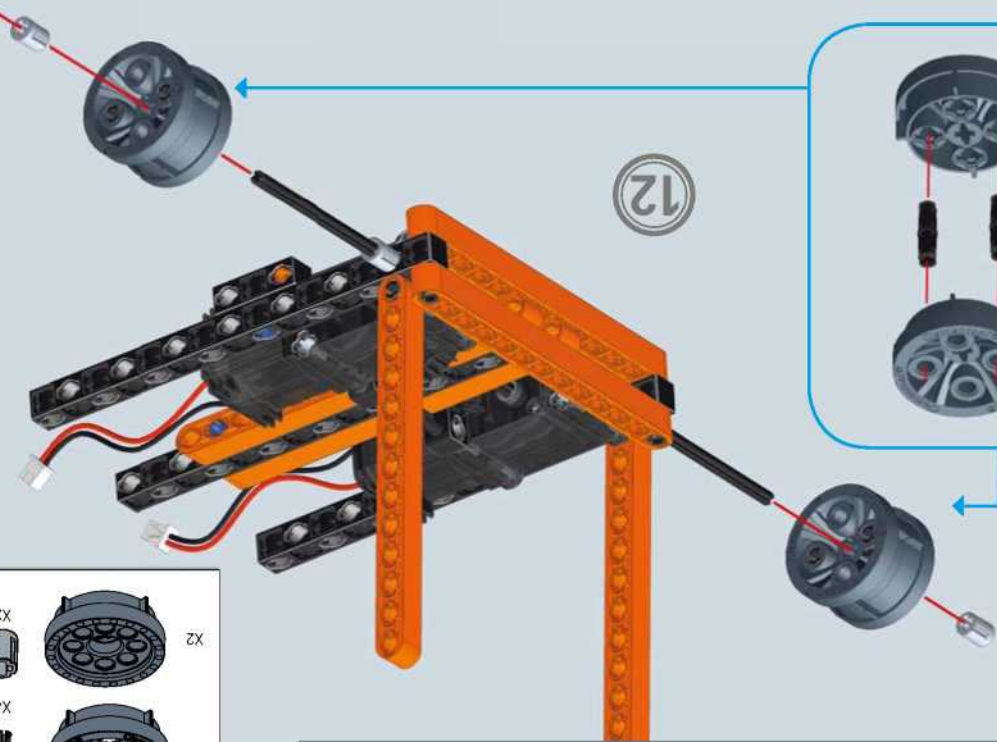
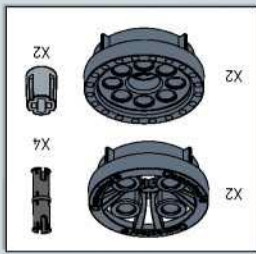
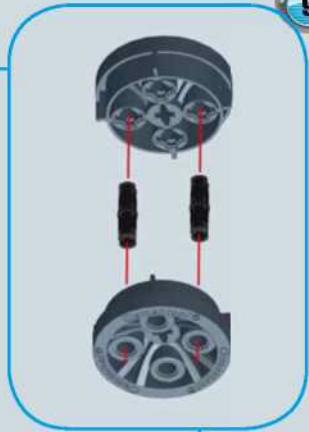
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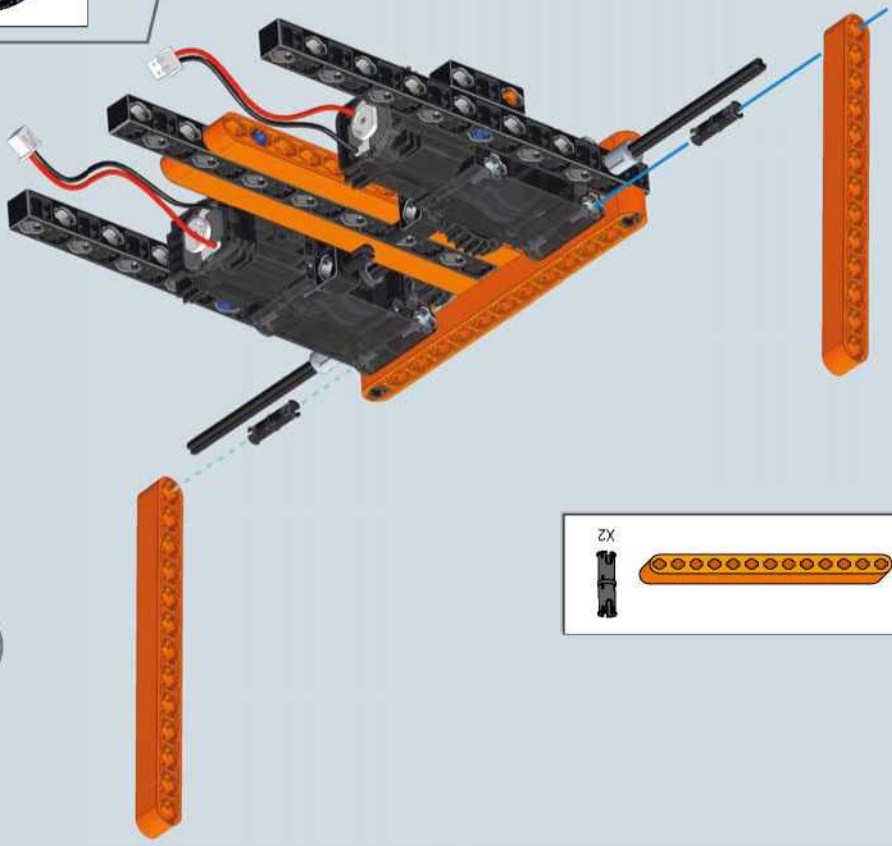
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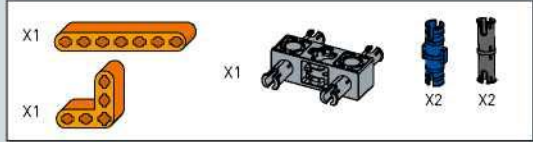
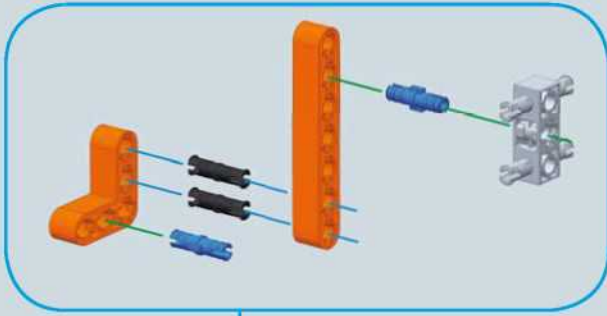


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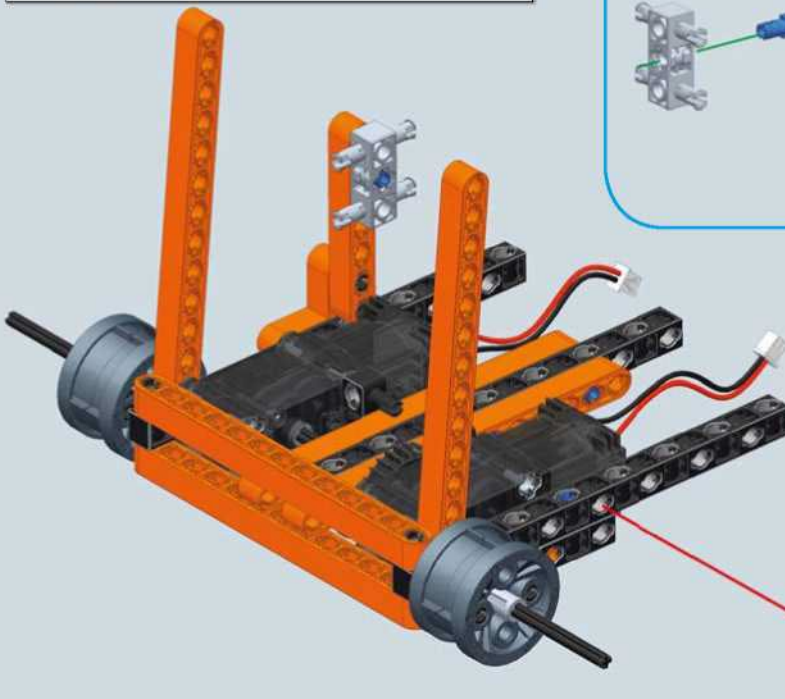
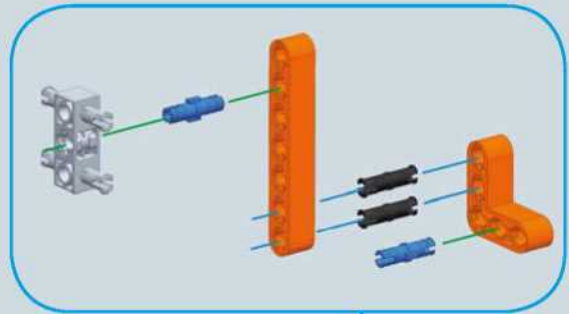
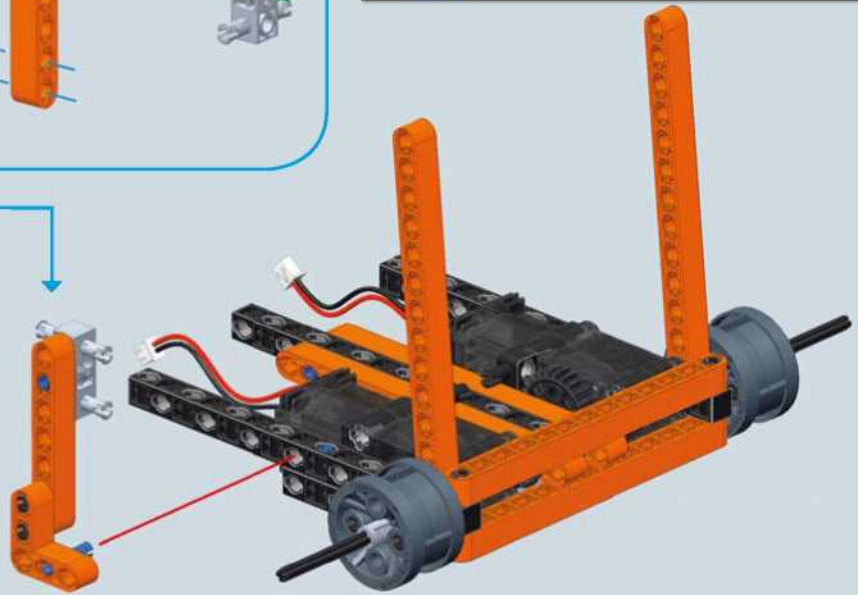


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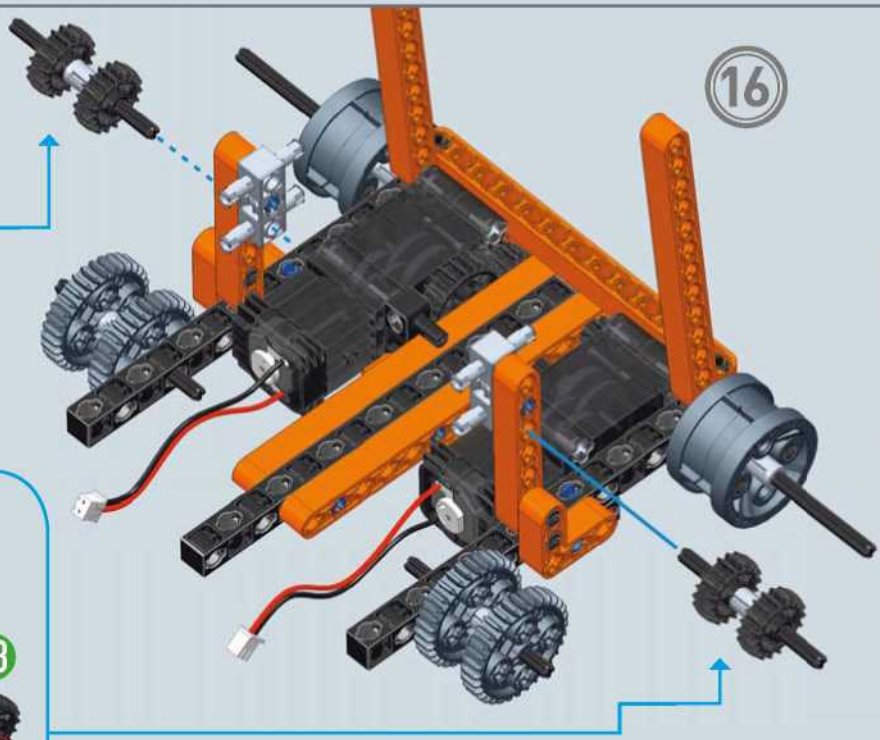
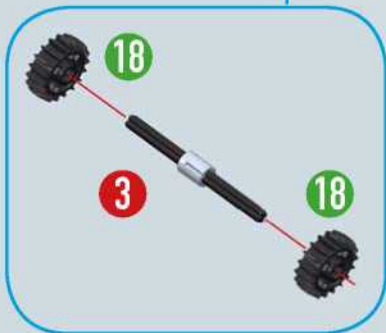
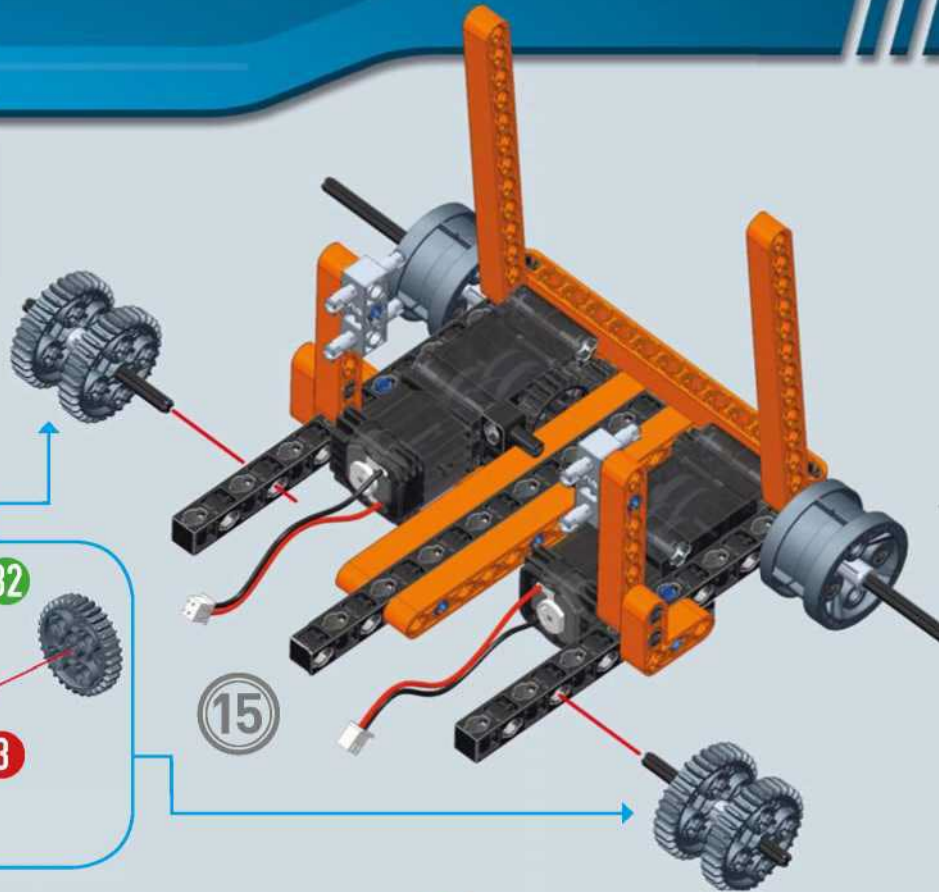
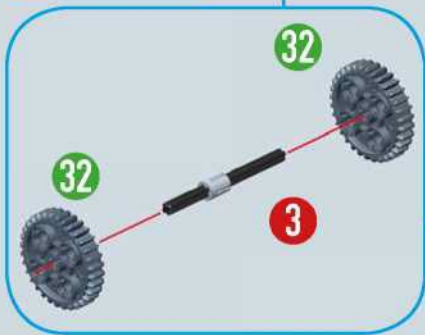




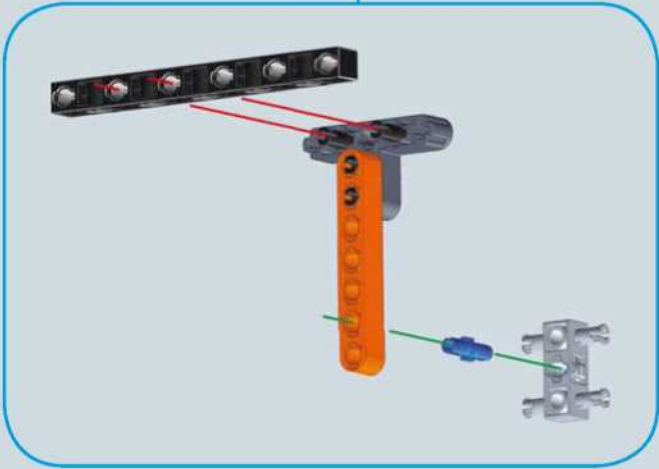
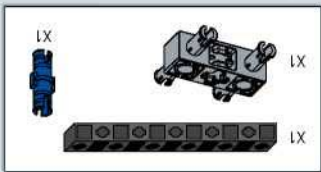
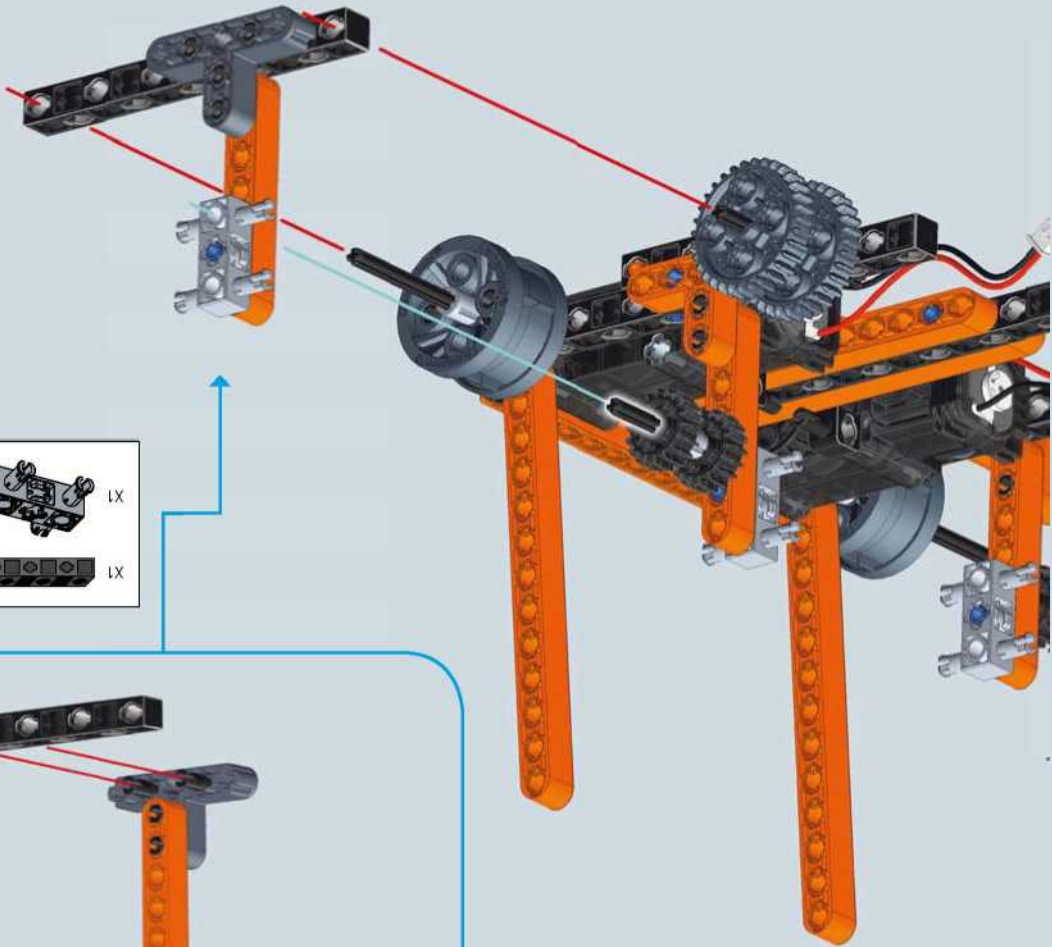
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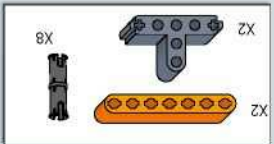
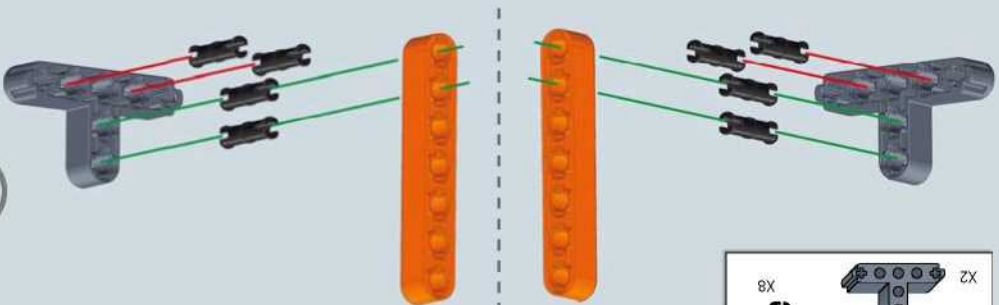




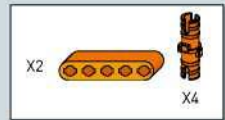
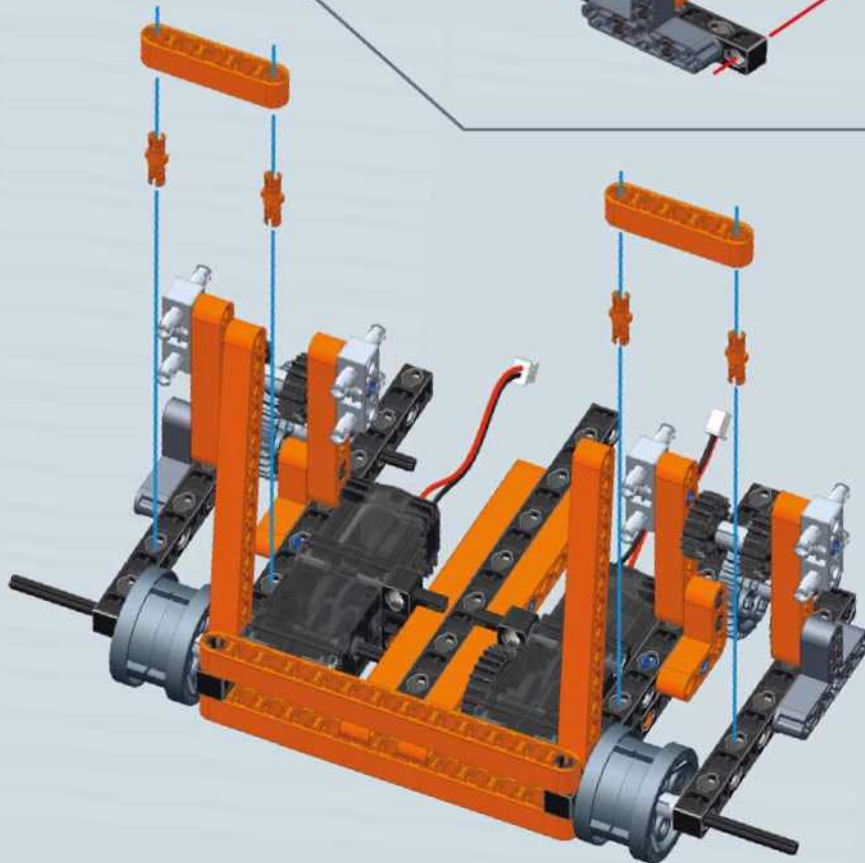
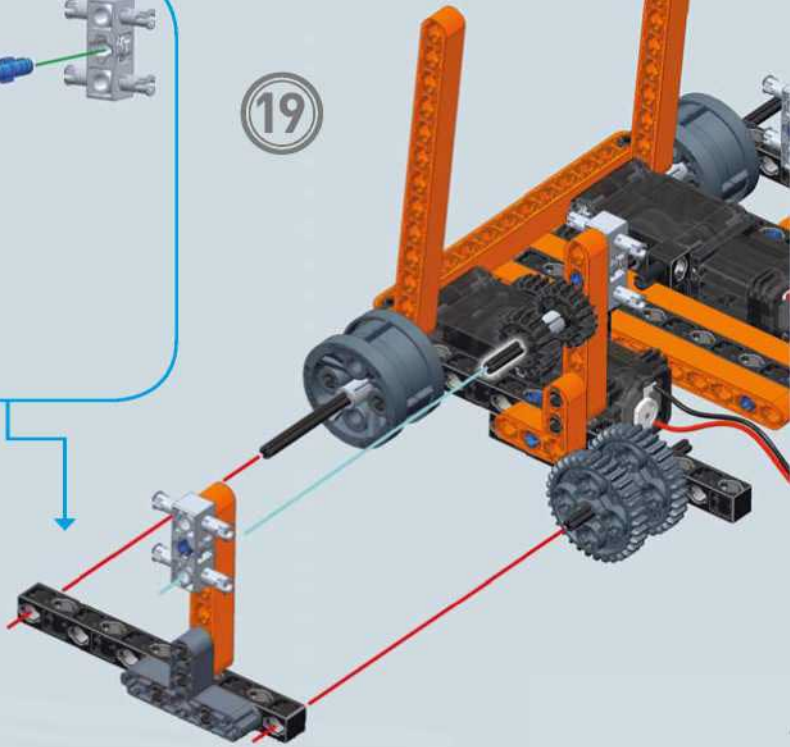
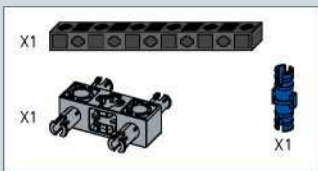
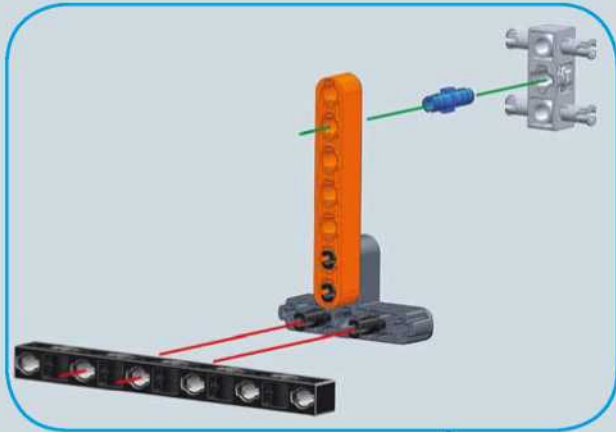


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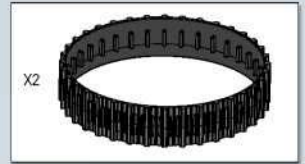
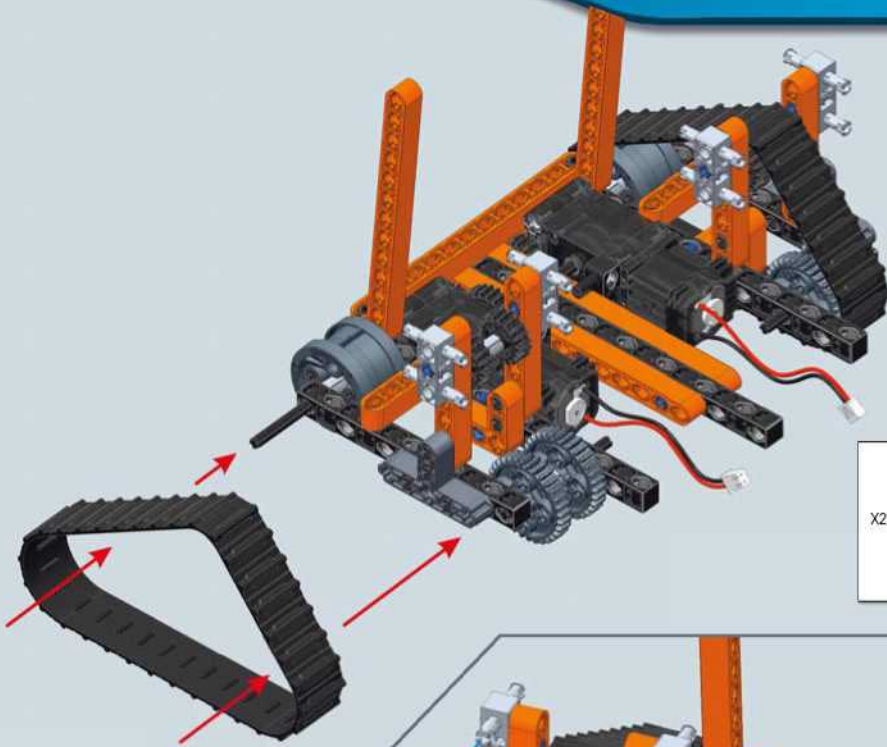


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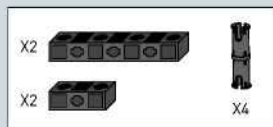
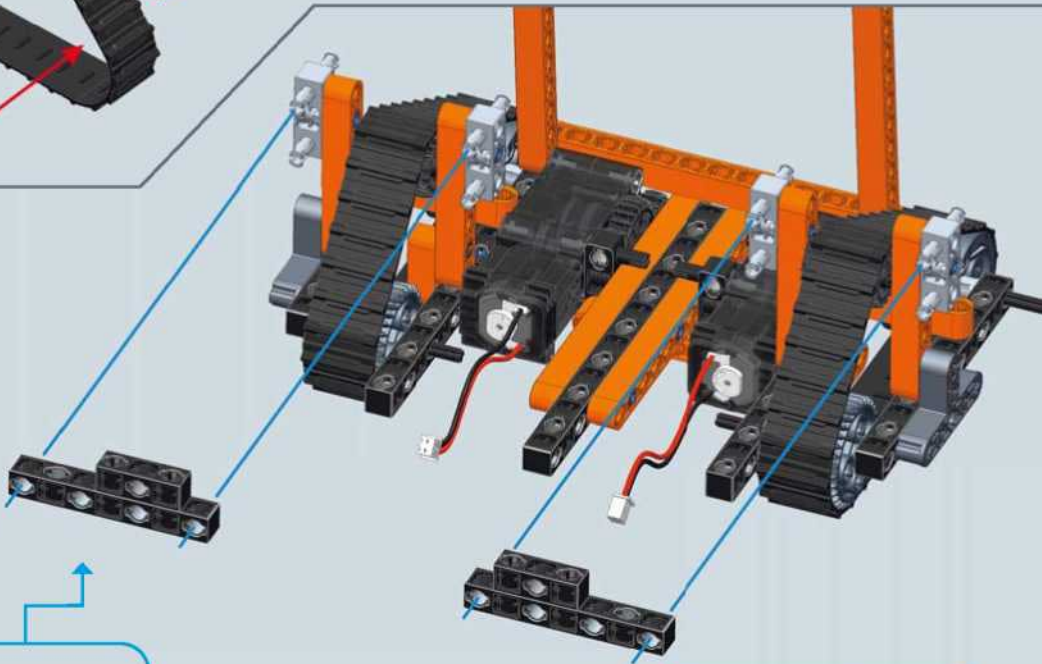


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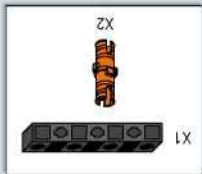
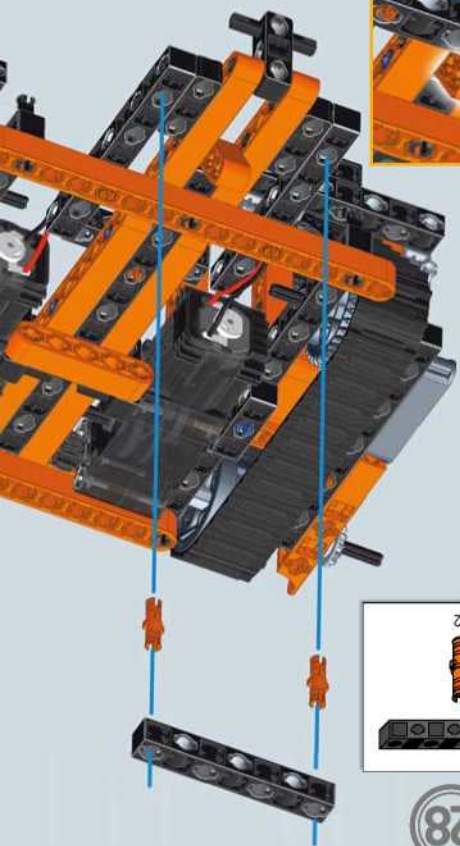
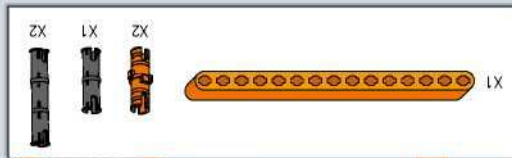


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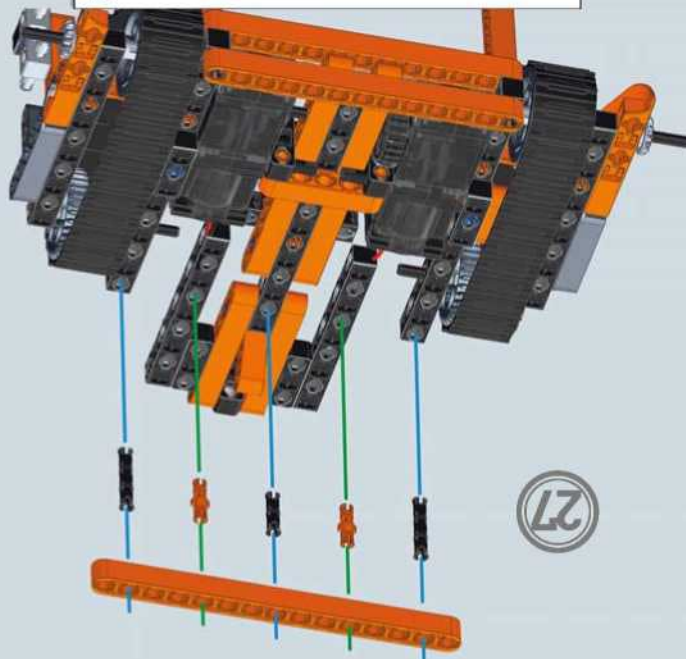




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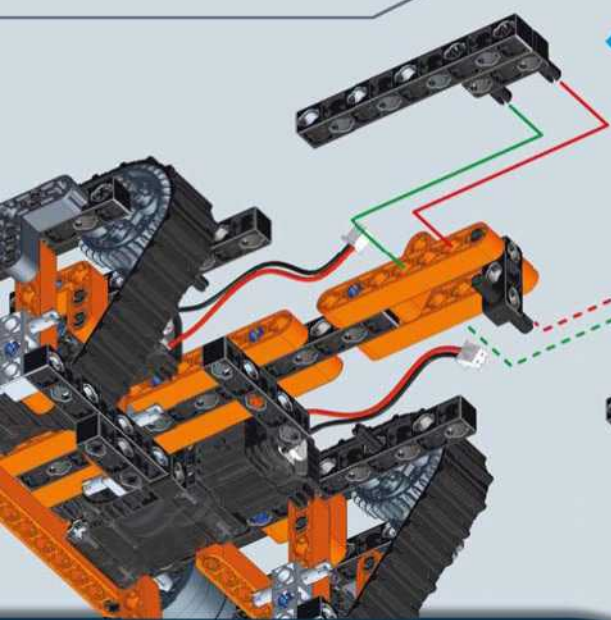
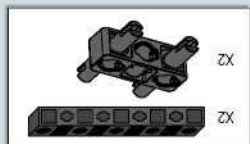
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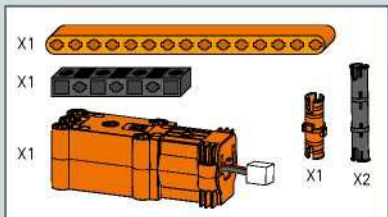


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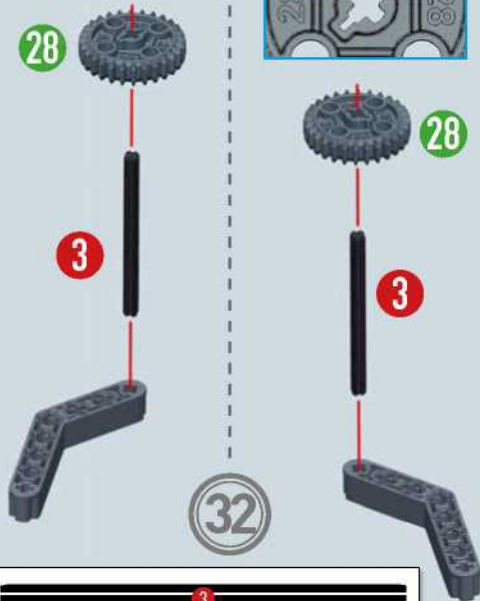
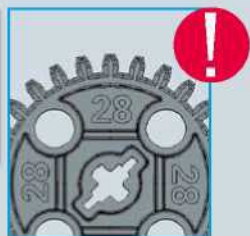
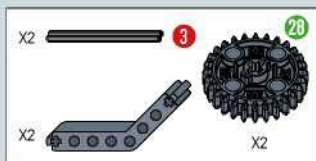
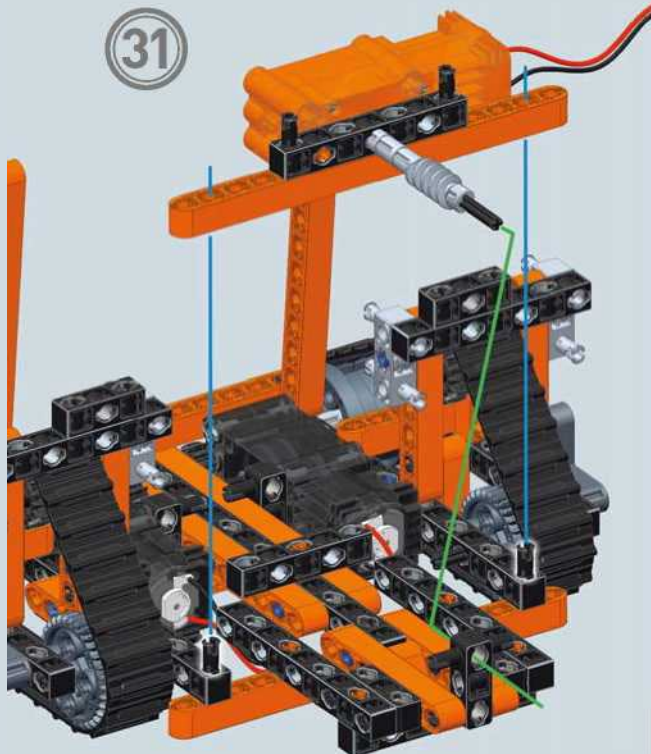
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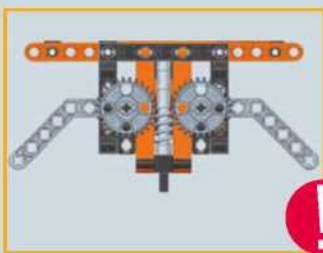


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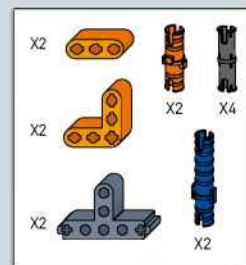
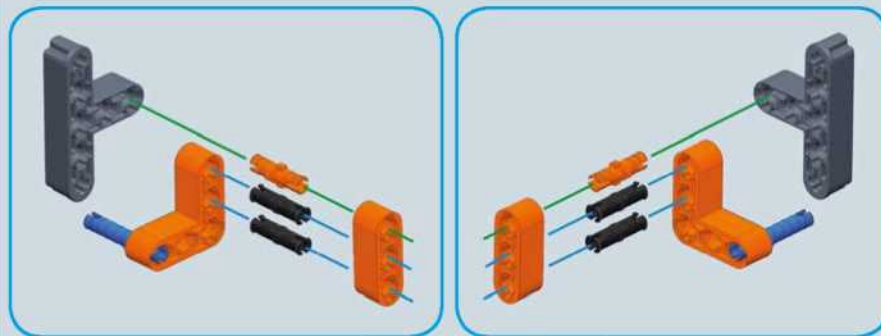


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Zkontrolujte, zda jsou tyče správně umístěny



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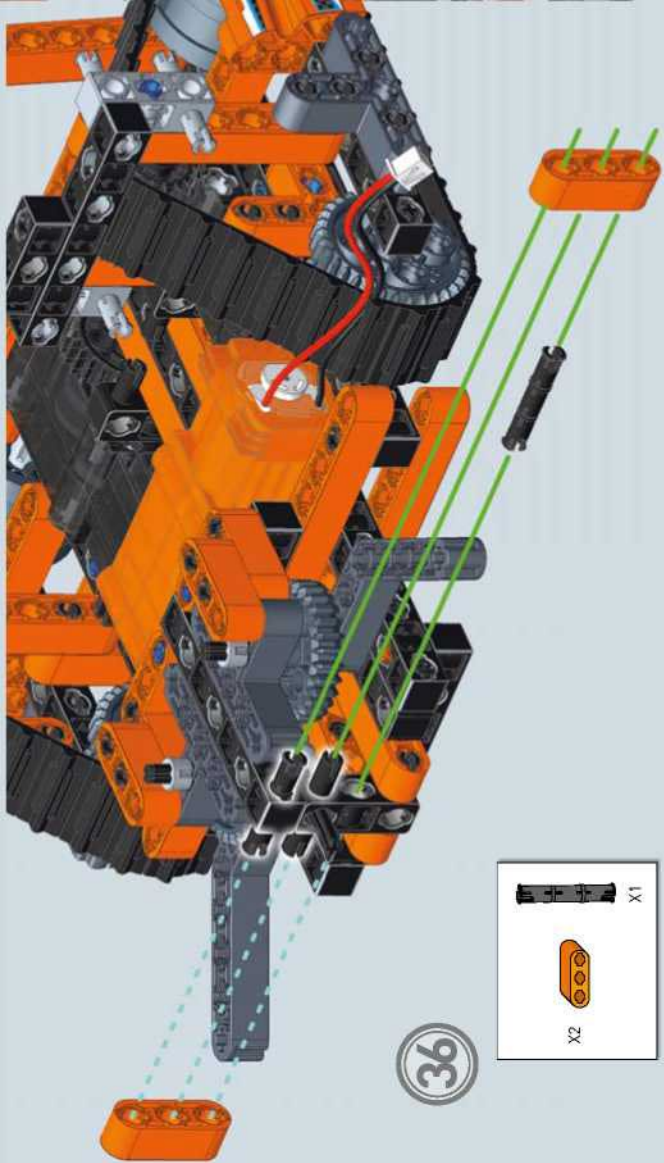
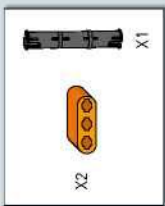


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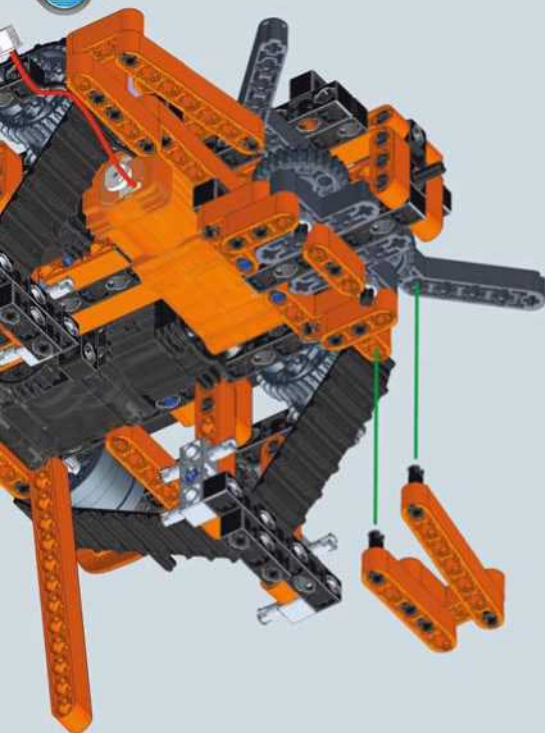
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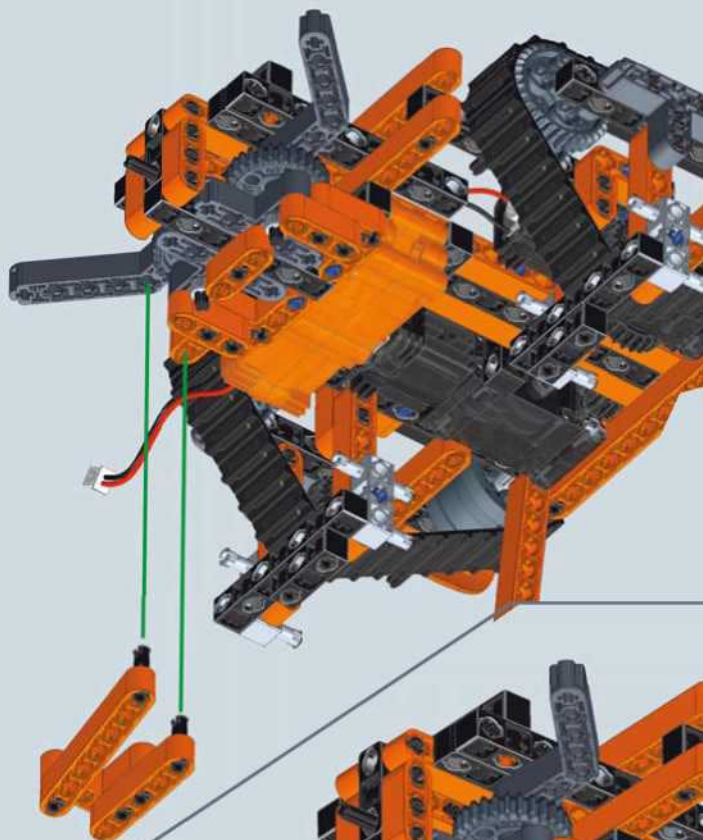
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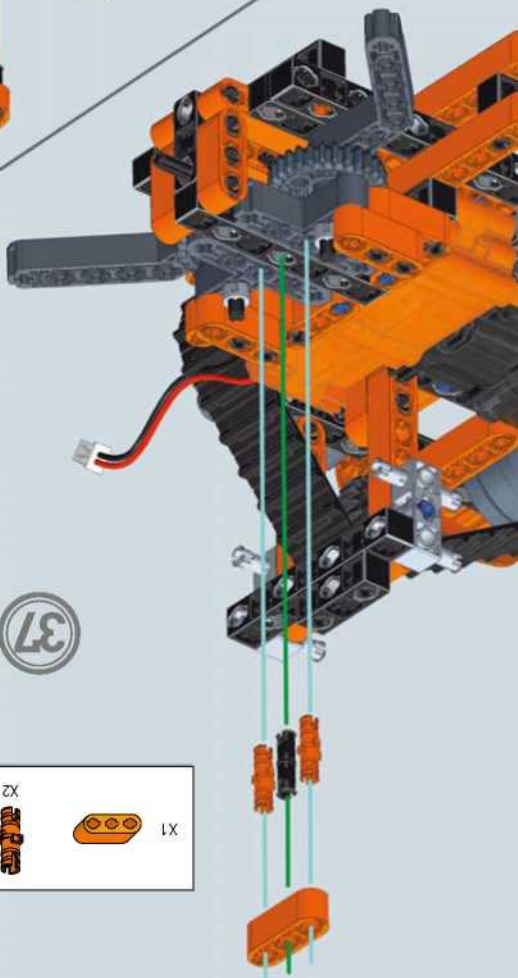




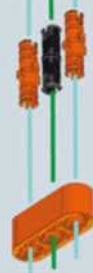
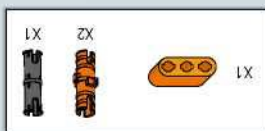
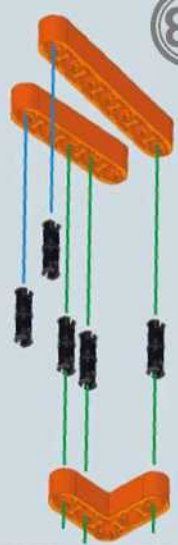
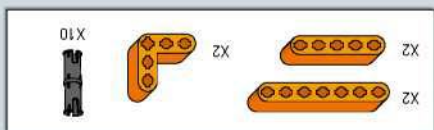
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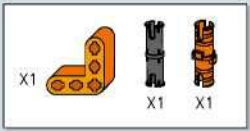
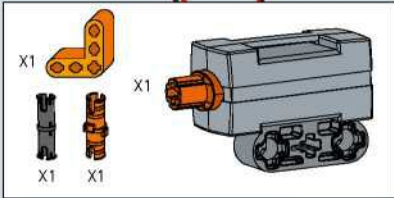
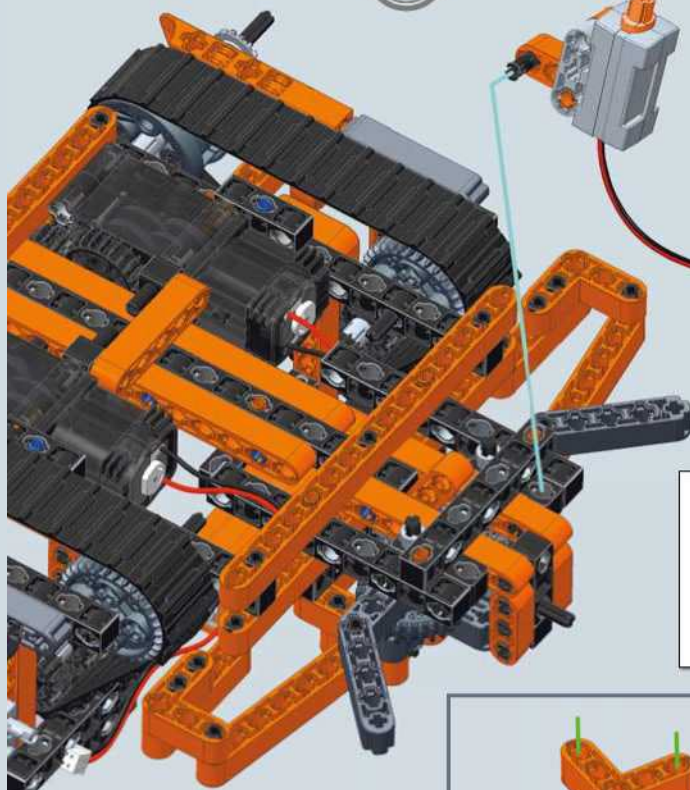
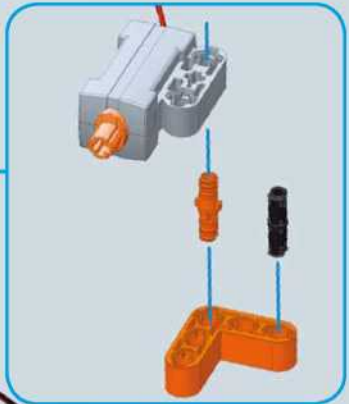
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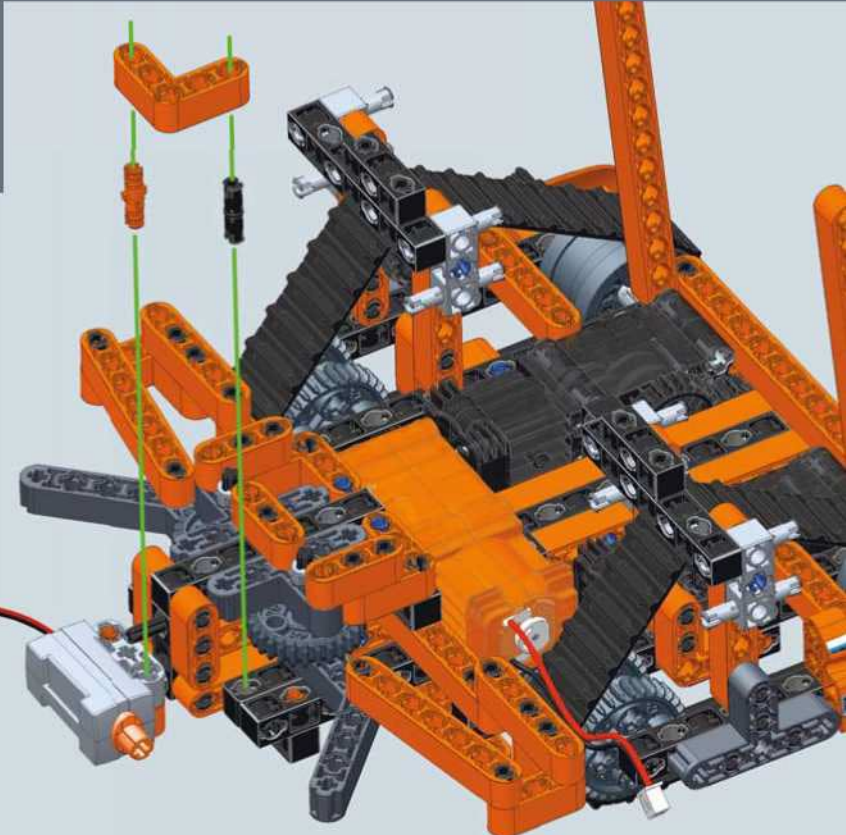
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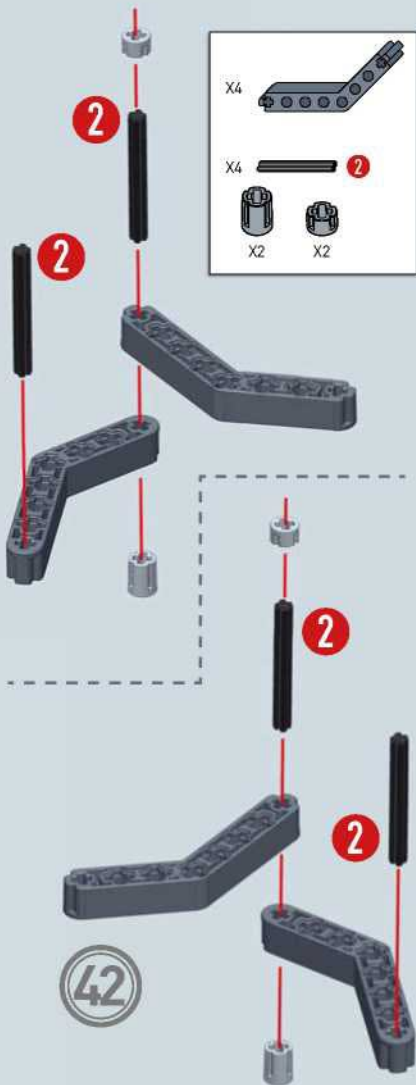


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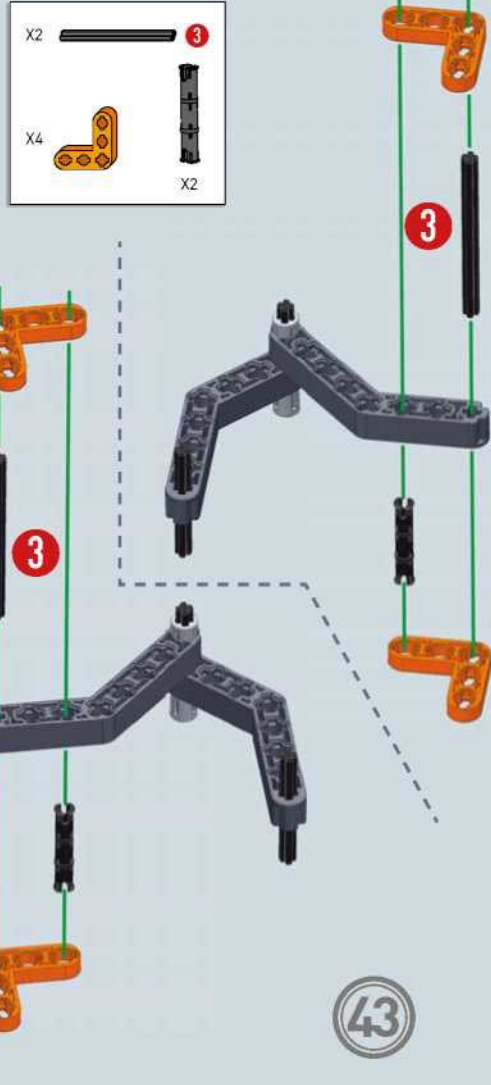
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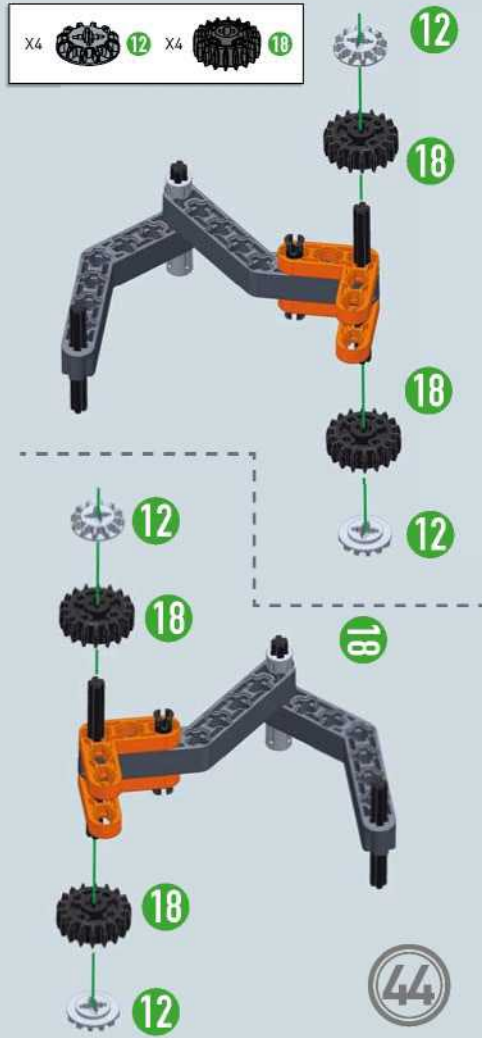
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1:1    

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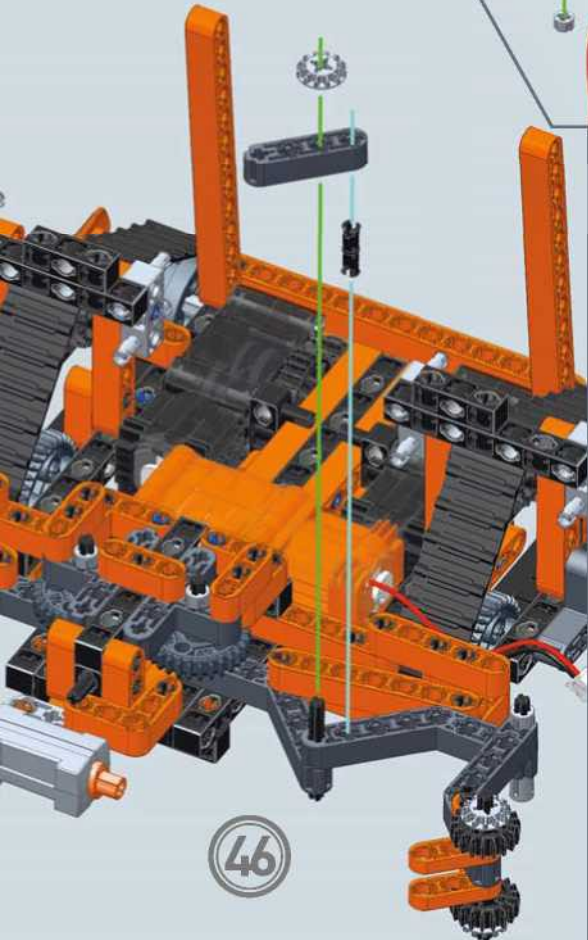
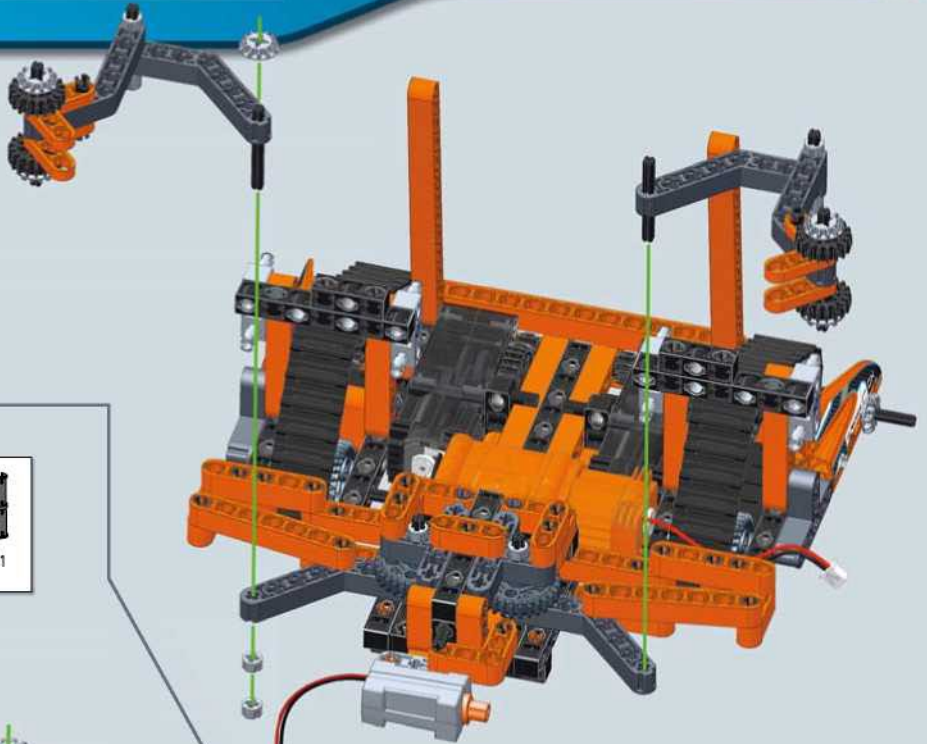
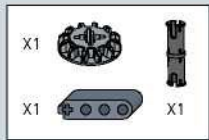
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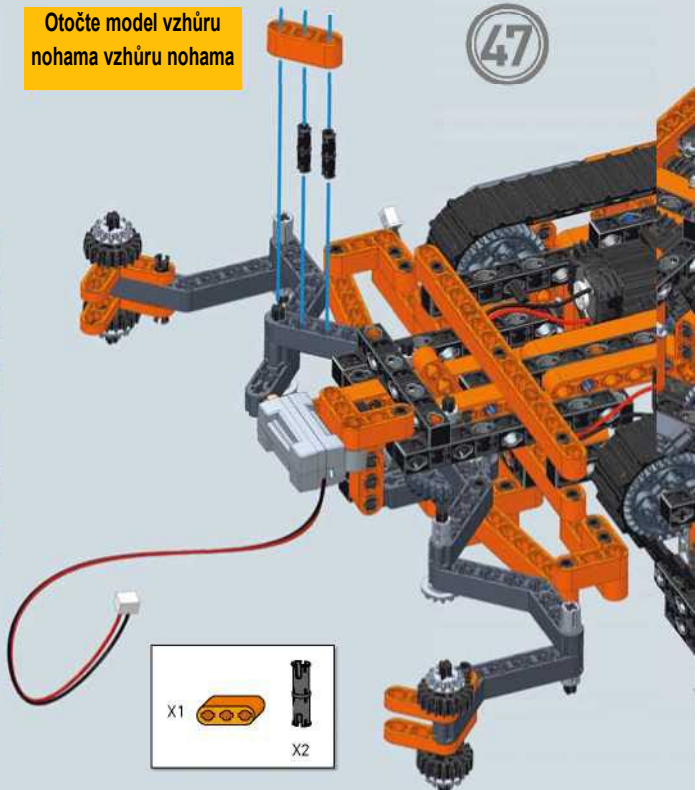
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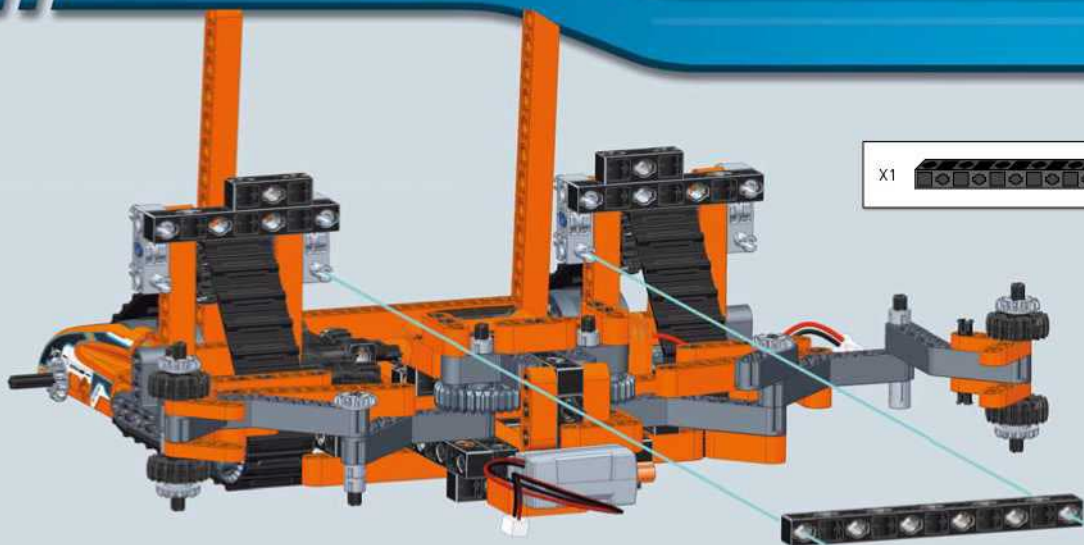


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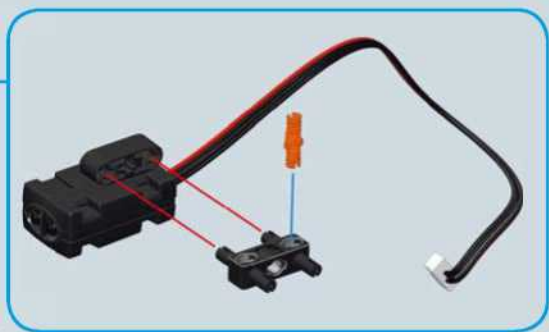
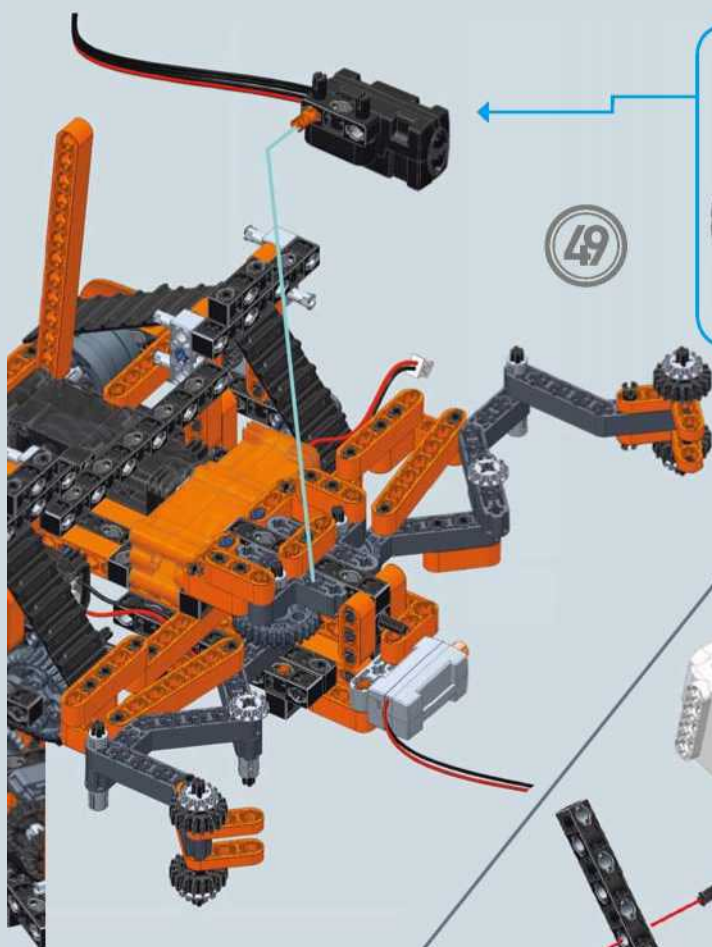
Otočte model vzhůru  
nohama vzhůru nohama

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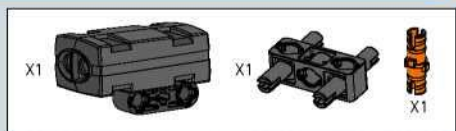




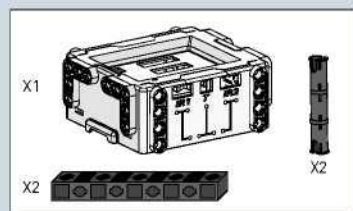
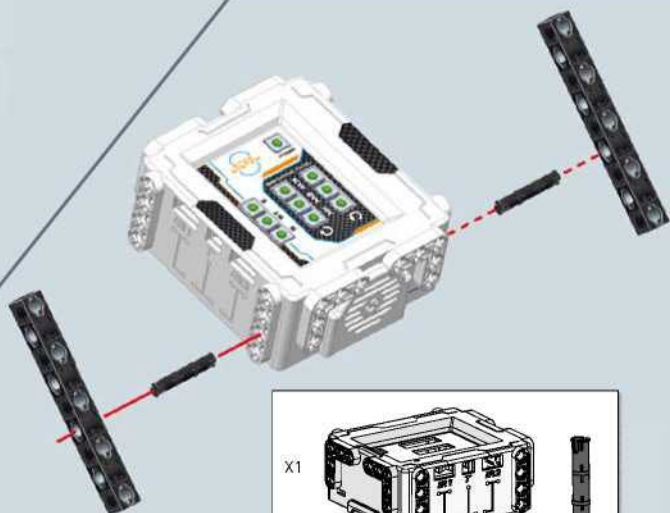
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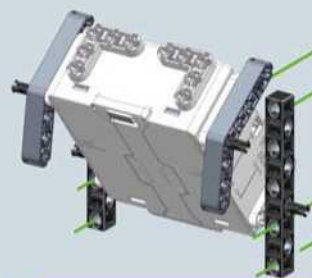
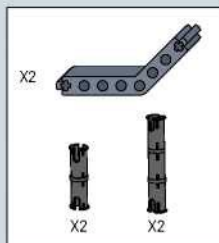
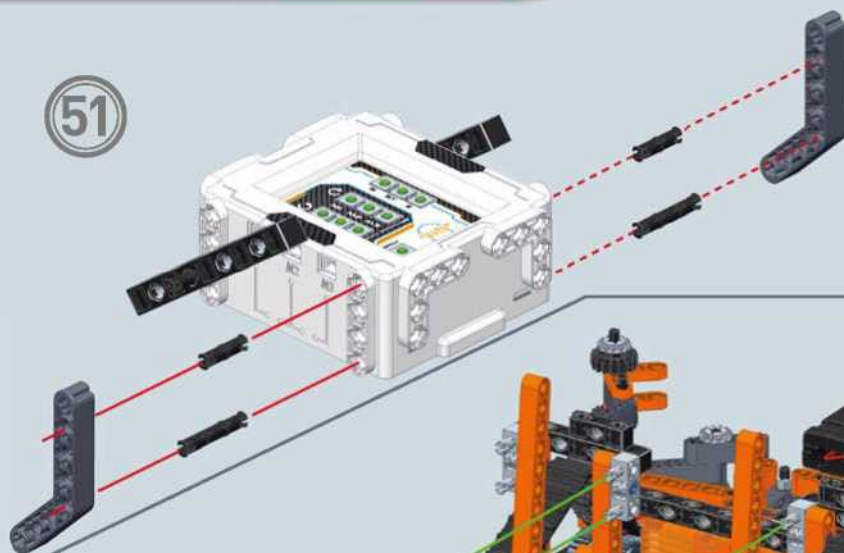


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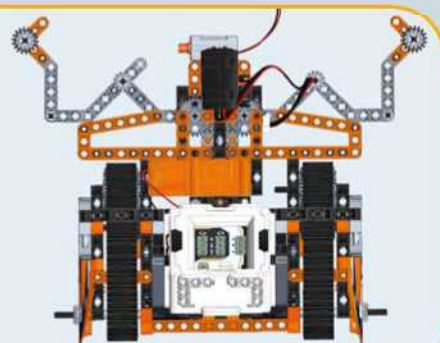
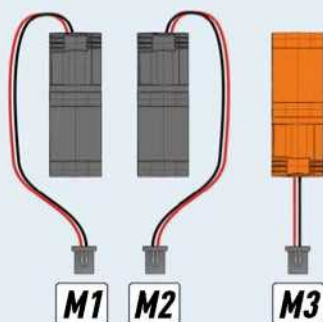
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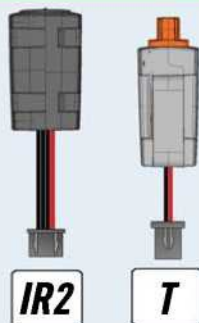
### PŘIPOJTE MOTORY K CENTRÁLNÍ MODUL

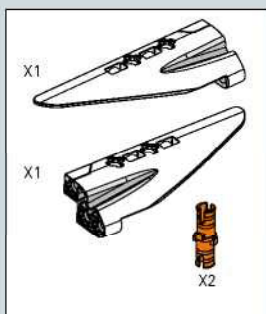
Umístěte model podle obrázku a připojte černý motor vlevo k portu M1 a černý motor vpravo k portu M2. Připojte oranžový motor k portu M3



### PŘIPOJENÍ SENZORŮ NA CENTRAL

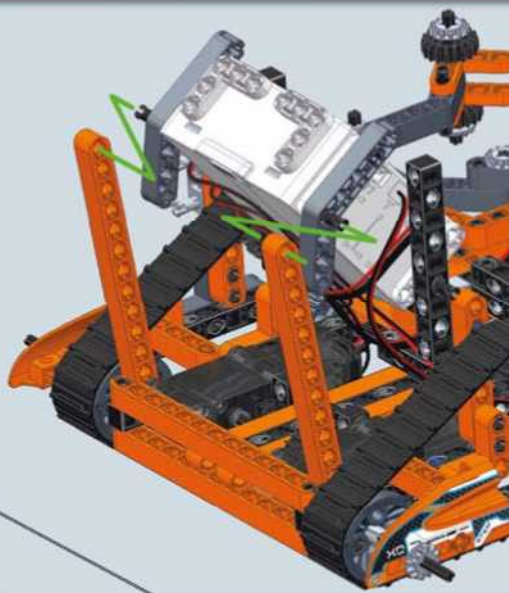
Připojte IR senzor k portu IR2. Připojte dotykový senzor k portu T.



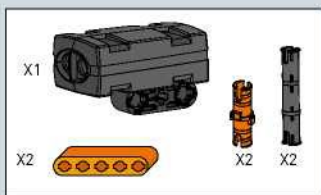
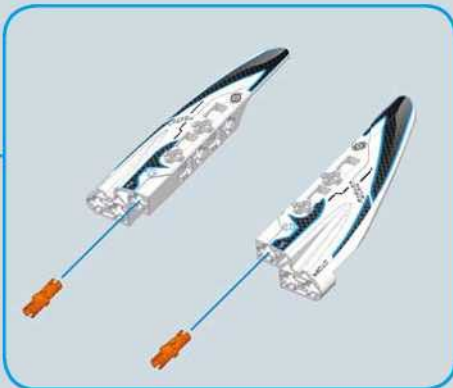


53

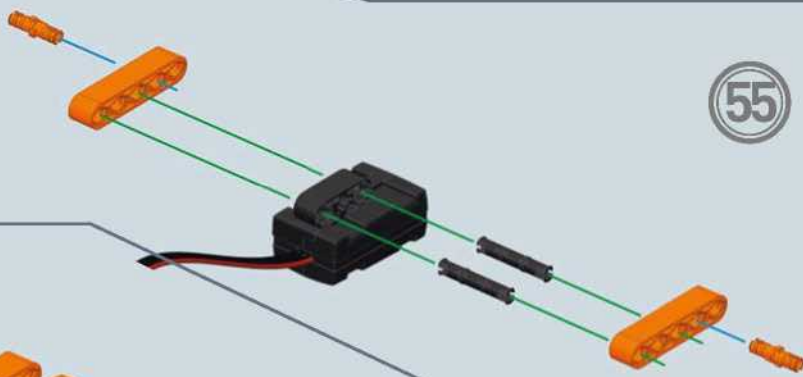
Připevněte modul ke dvěma oranžovým tyčím.



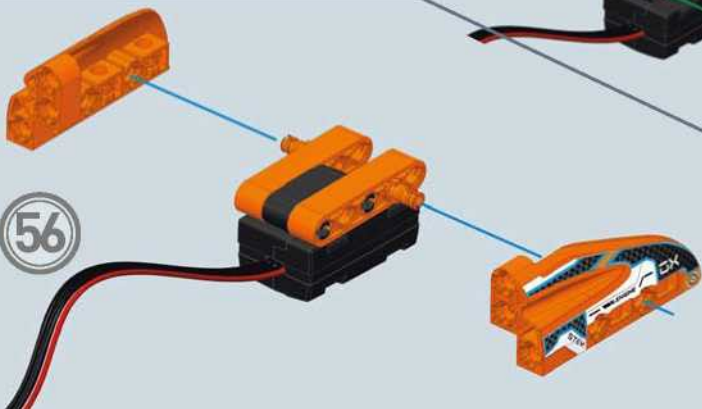
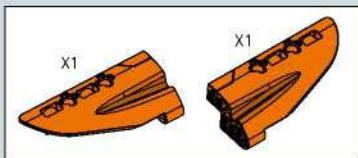
54

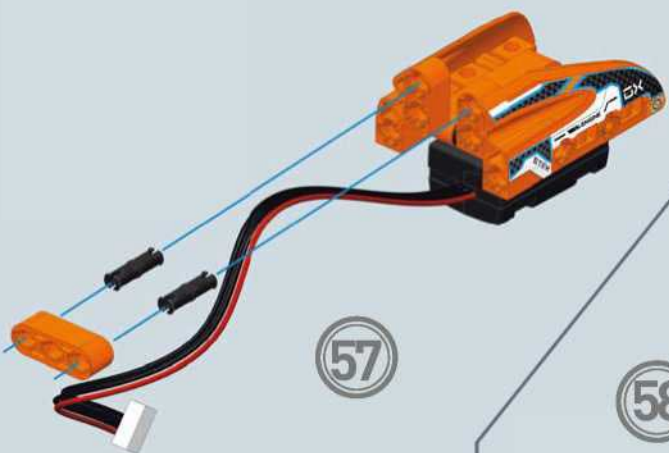


55

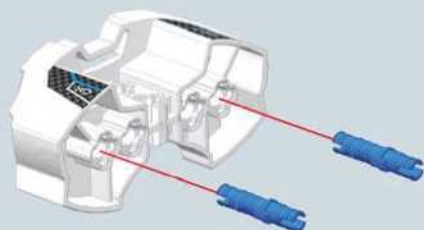
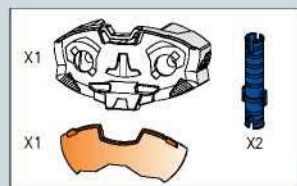


56

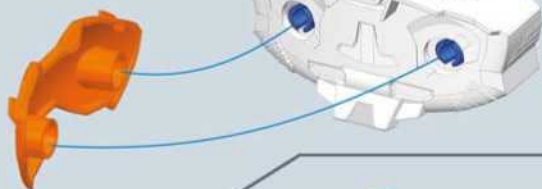




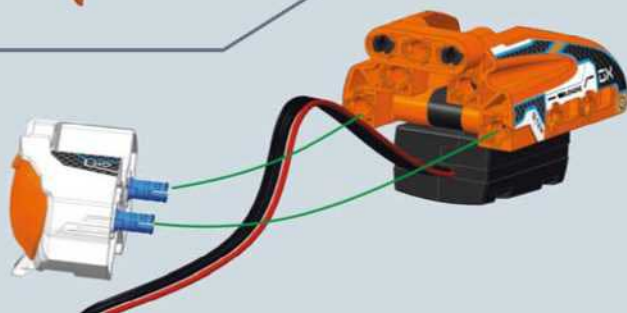
57



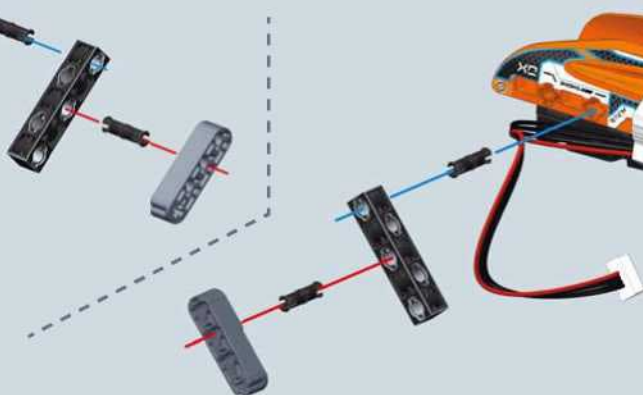
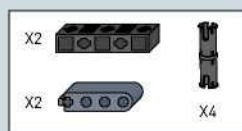
58



59

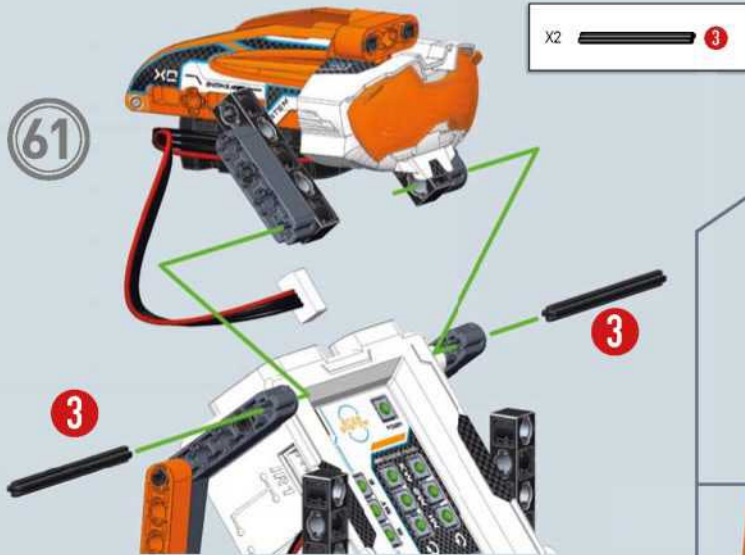


60





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1:1 

### PŘIPOJENÍ SENZORU K CENTRÁLNÍ JEDNOTCE

Připojte IR senzor k portu IR1.



IR1



X1

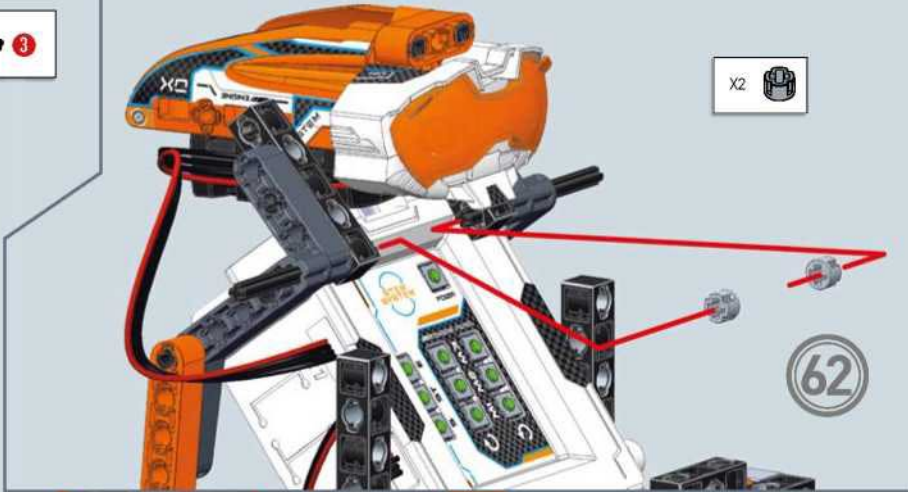


X1

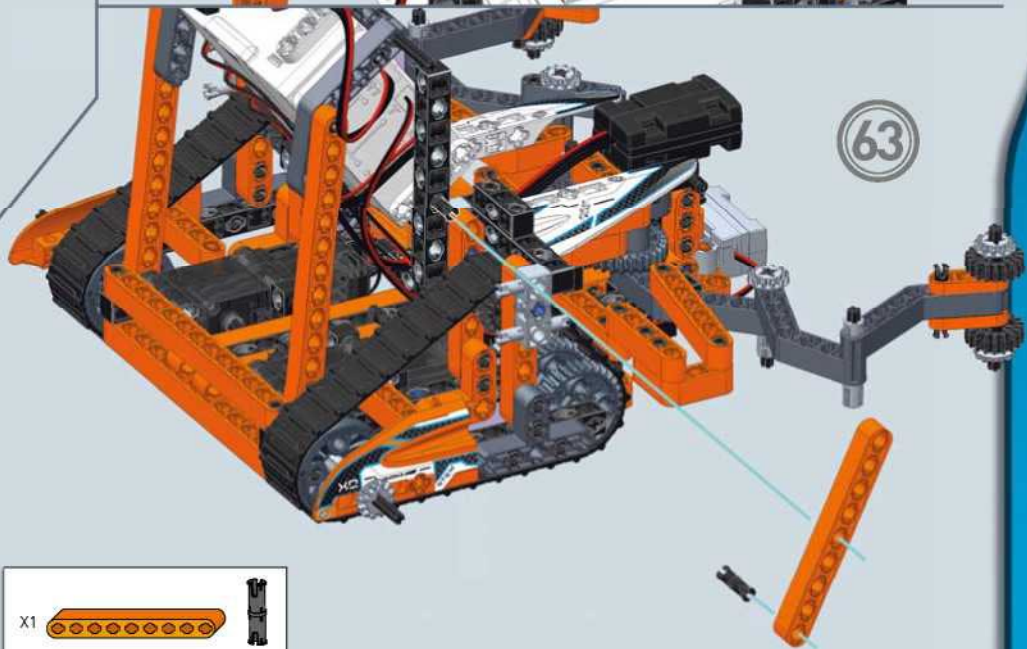
X2



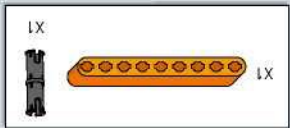
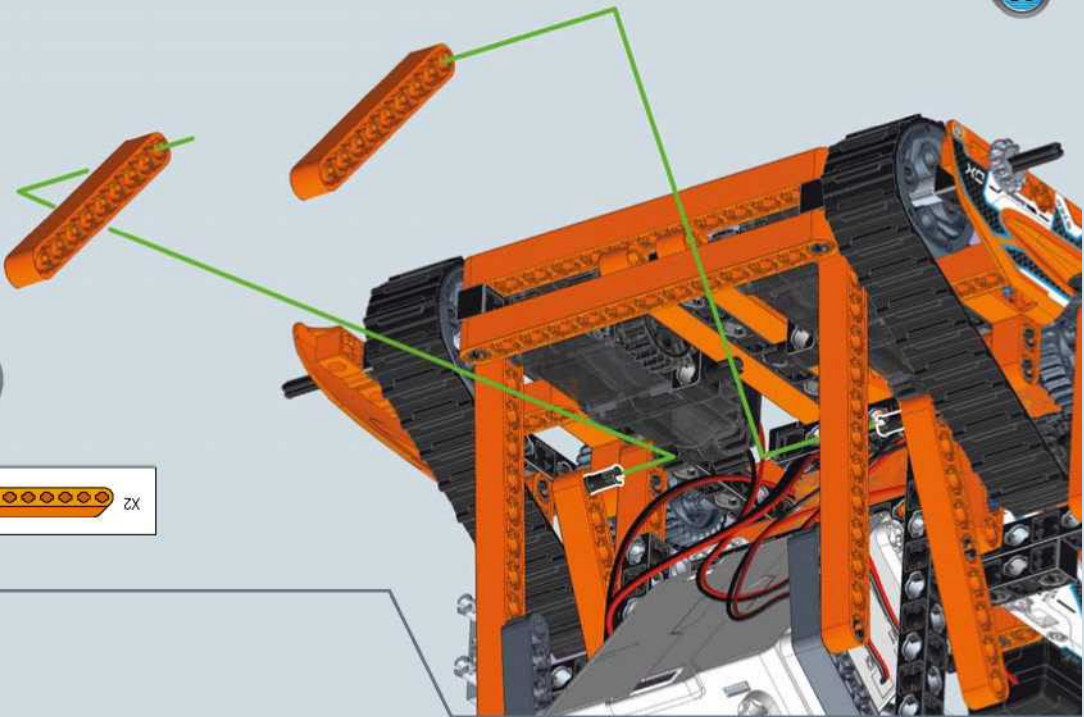
62



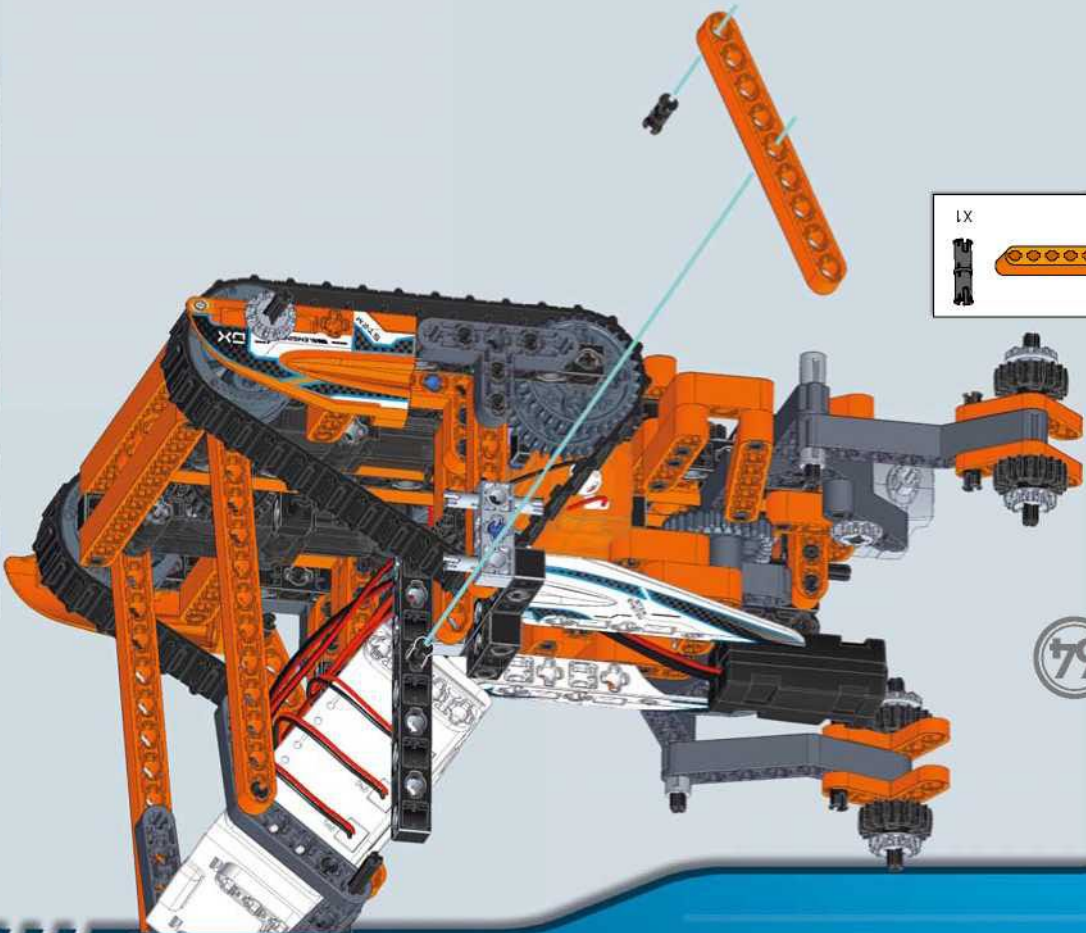
63

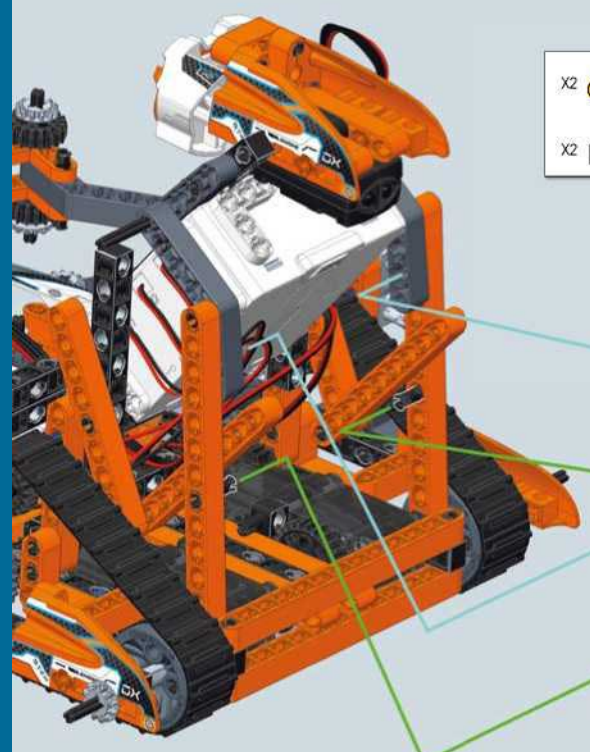


65



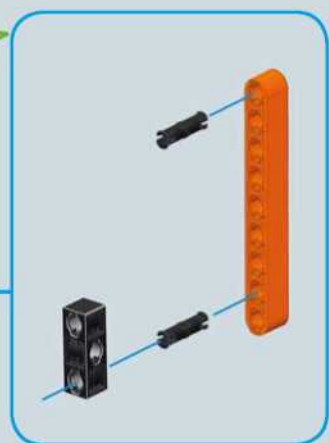
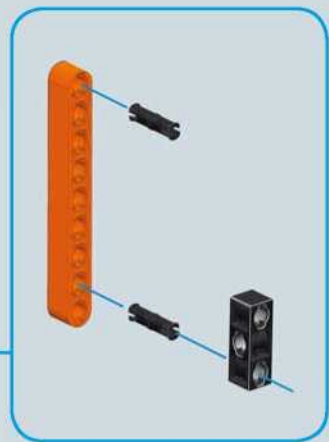
79



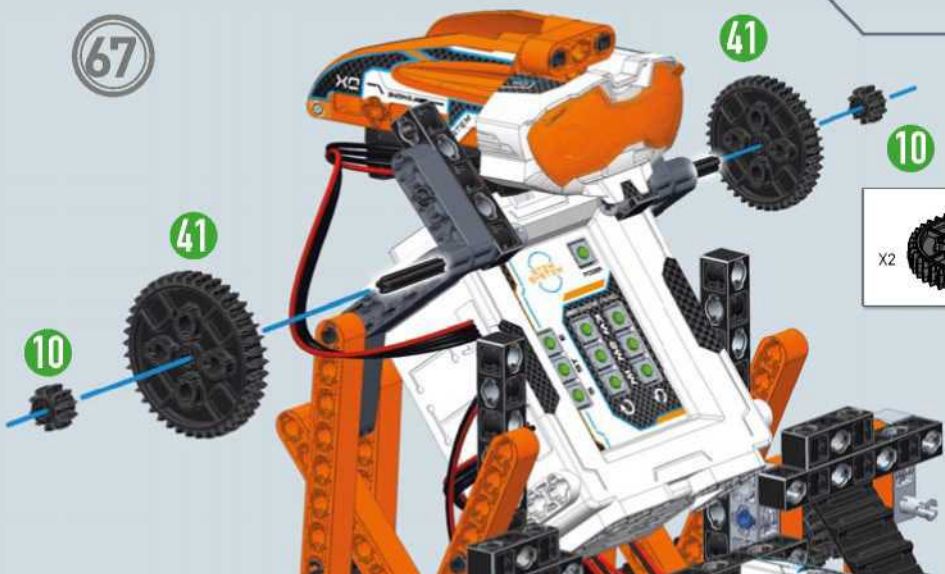


- X2
- X2
- X6

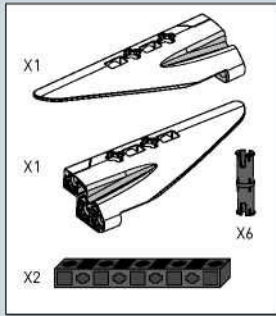
66



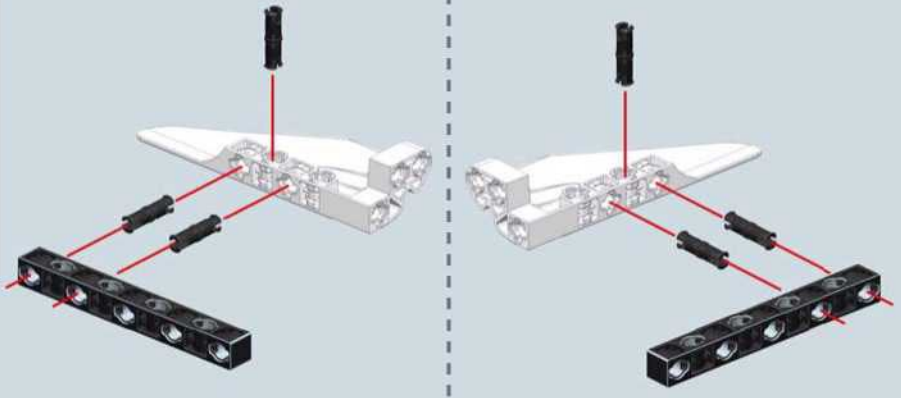
67



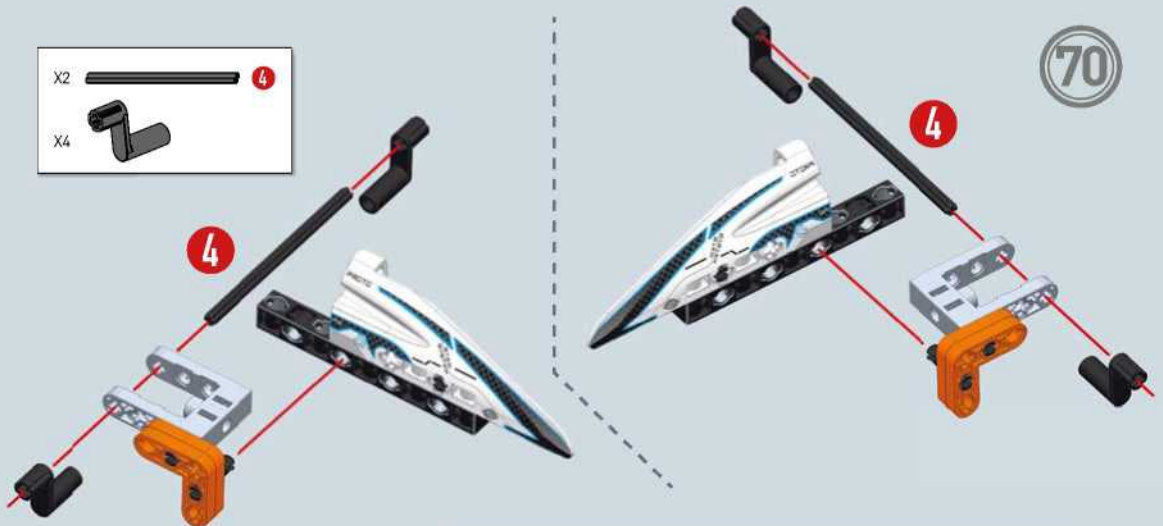
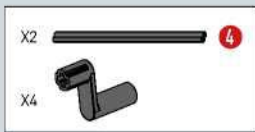
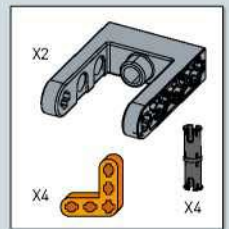
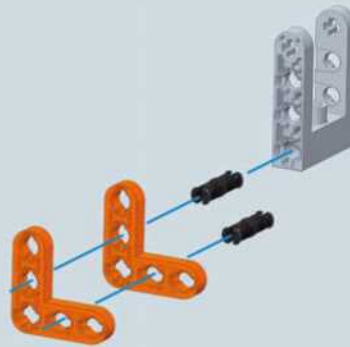
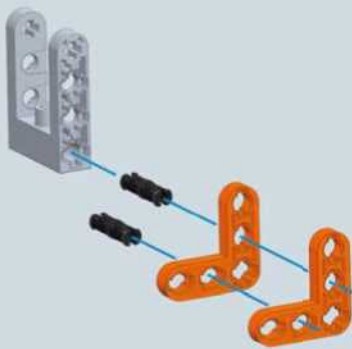
- X2
- X2



68



69



70



71



72



DOKONČENÝ MODEL

